

Local Regulation of Interchange Turbulence in a Dipole-Confined Plasma Torus using Current- Collection Feedback

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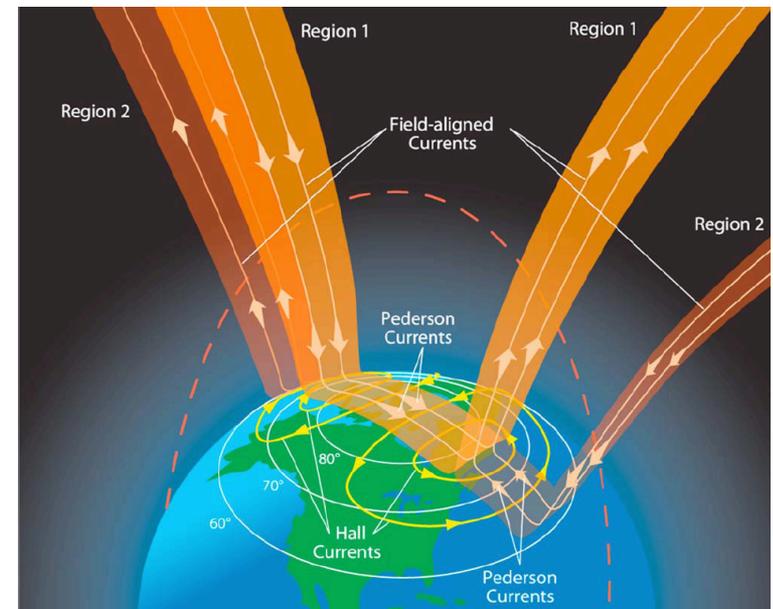
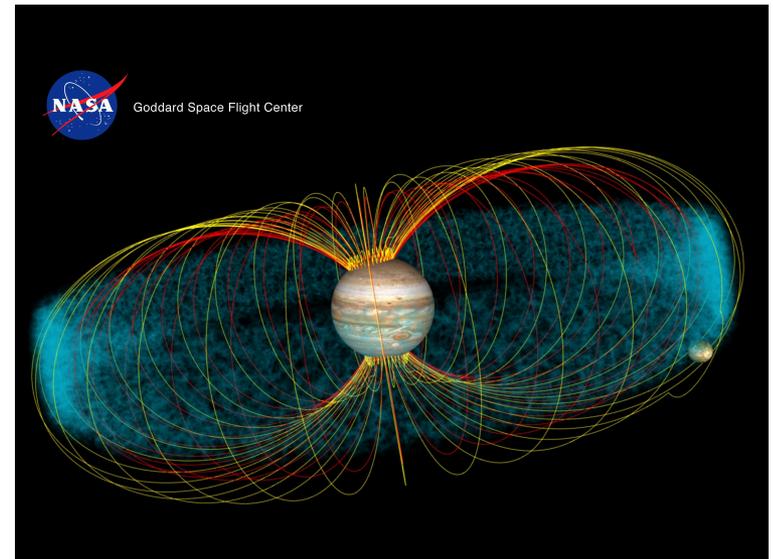


- Introduction
 - Magnetospheric Configurations in Space and the Lab
 - CTX Device and Interchange Turbulence
- Current-Collection Feedback in CTX
- Four Types of Experiments
 - Coherent Current-Collection (feed-forward)
 - Triggered Feedback
 - Gain and Phase Scans
 - Varying Sensor and Electrode Positions
- Linear Flux-Tube Averaged Gyro-Fluid Model
- Ongoing Work and Conclusion

Planetary Magnetospheres **have** Field-Aligned Currents



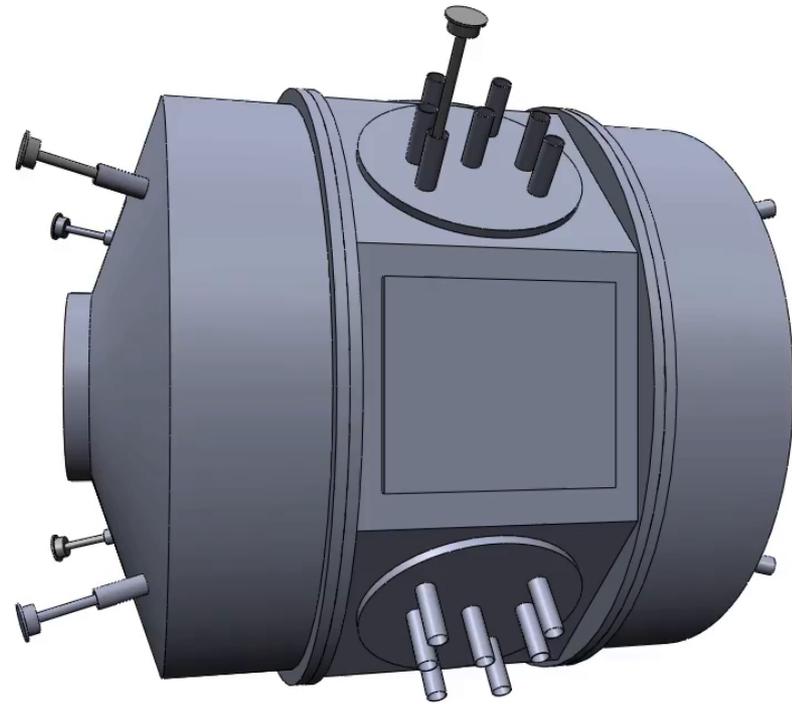
- Planetary magnetospheres have dipolar magnetic geometries.
- Solar wind drives steady magnetospheric convection.
- Cross-field conductivity is much higher in the ionosphere.
- Field aligned currents couple these systems.
- Magnetospheric generator is **regulated** by ionospheric load.



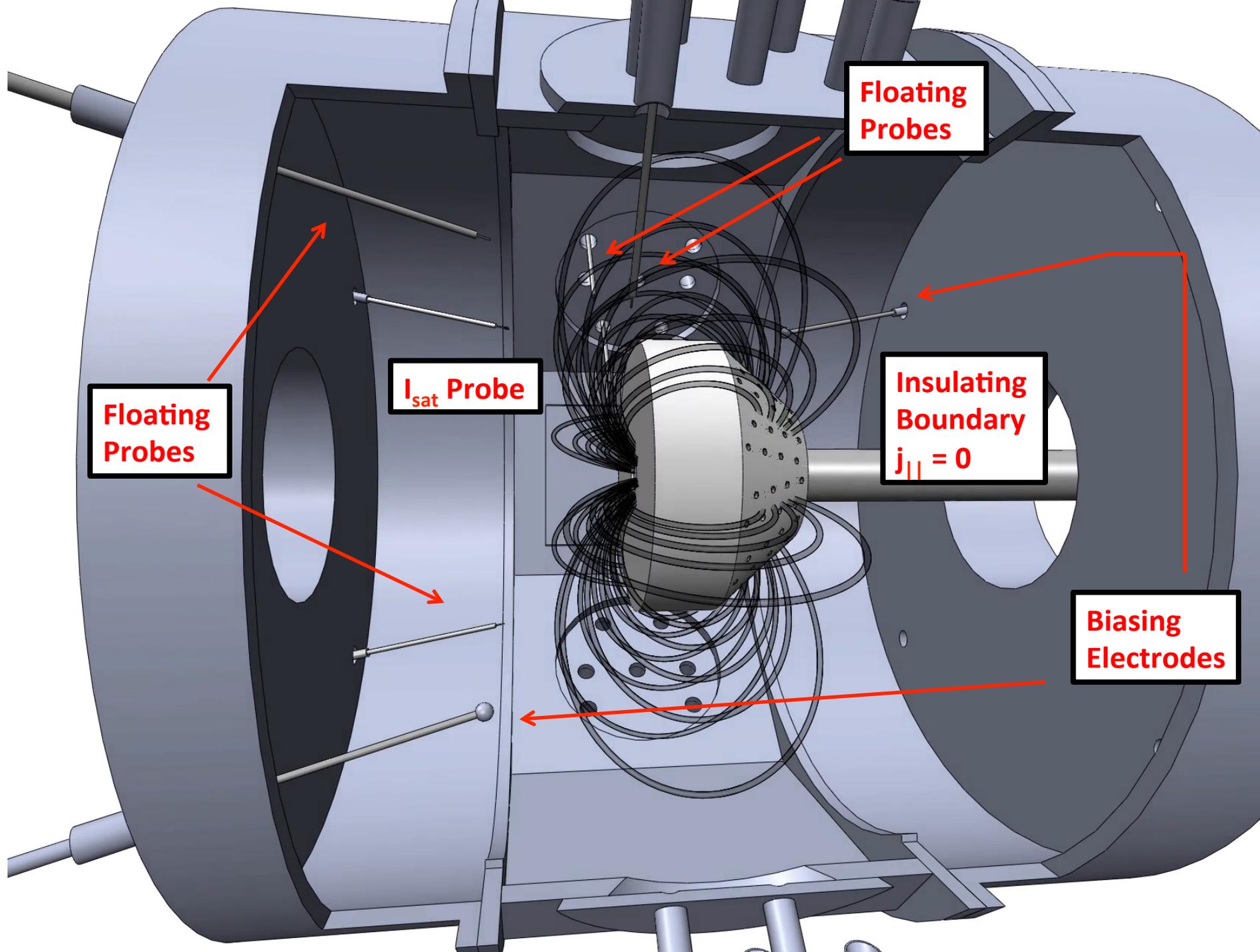
- LDX has a levitated superconducting coil with closed field lines, no parallel currents
- CTX has insulating polar caps which prevent field aligned currents.
- **New Result:** Controlled addition of current to individual flux-tubes allows us to explore the response of global interchange motion.

Like a “controlled ionosphere”





1.5 m



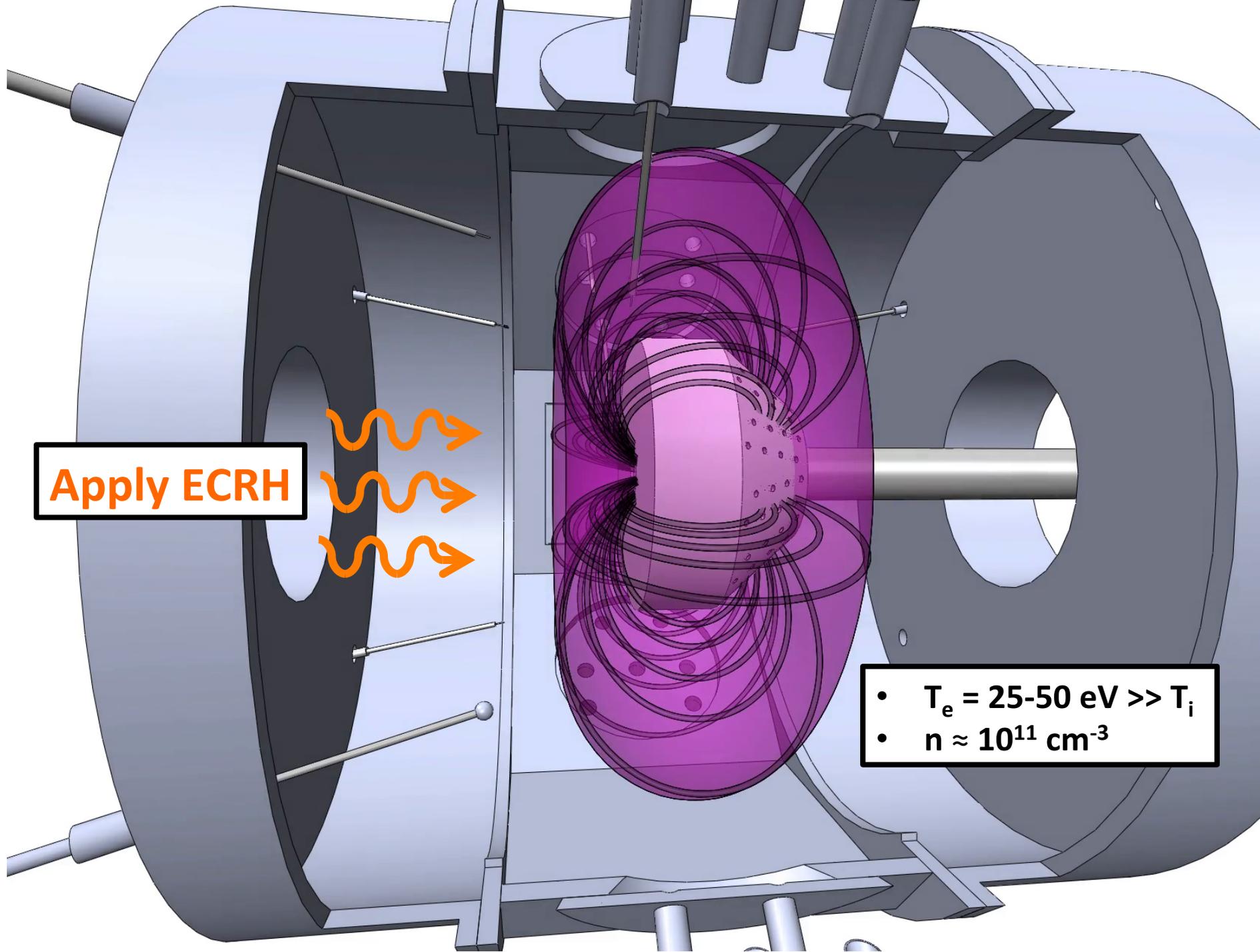
Floating Probes

Floating Probes

I_{sat} Probe

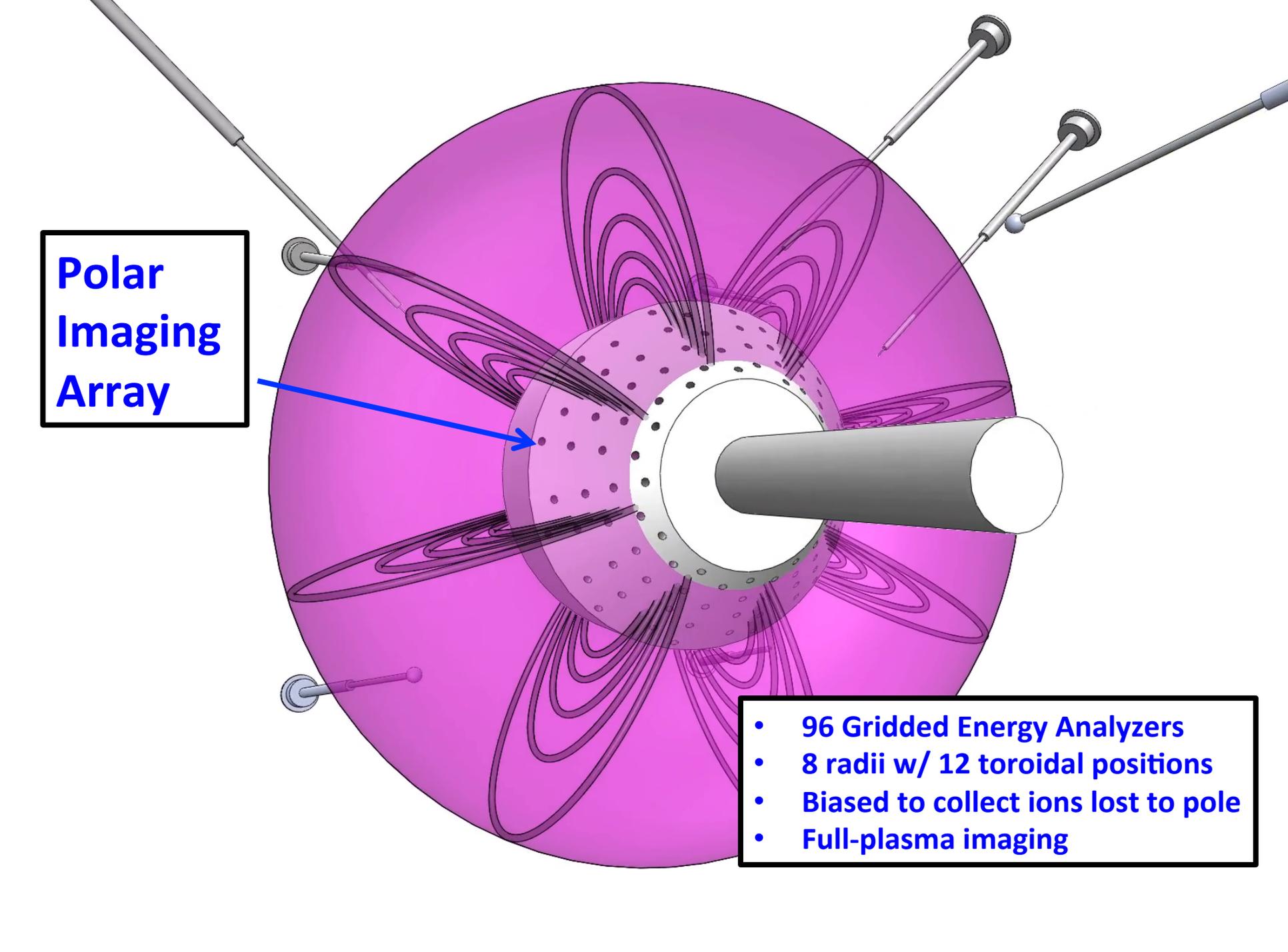
Insulating Boundary
 $j_{||} = 0$

Biasing Electrodes



Apply ECRH

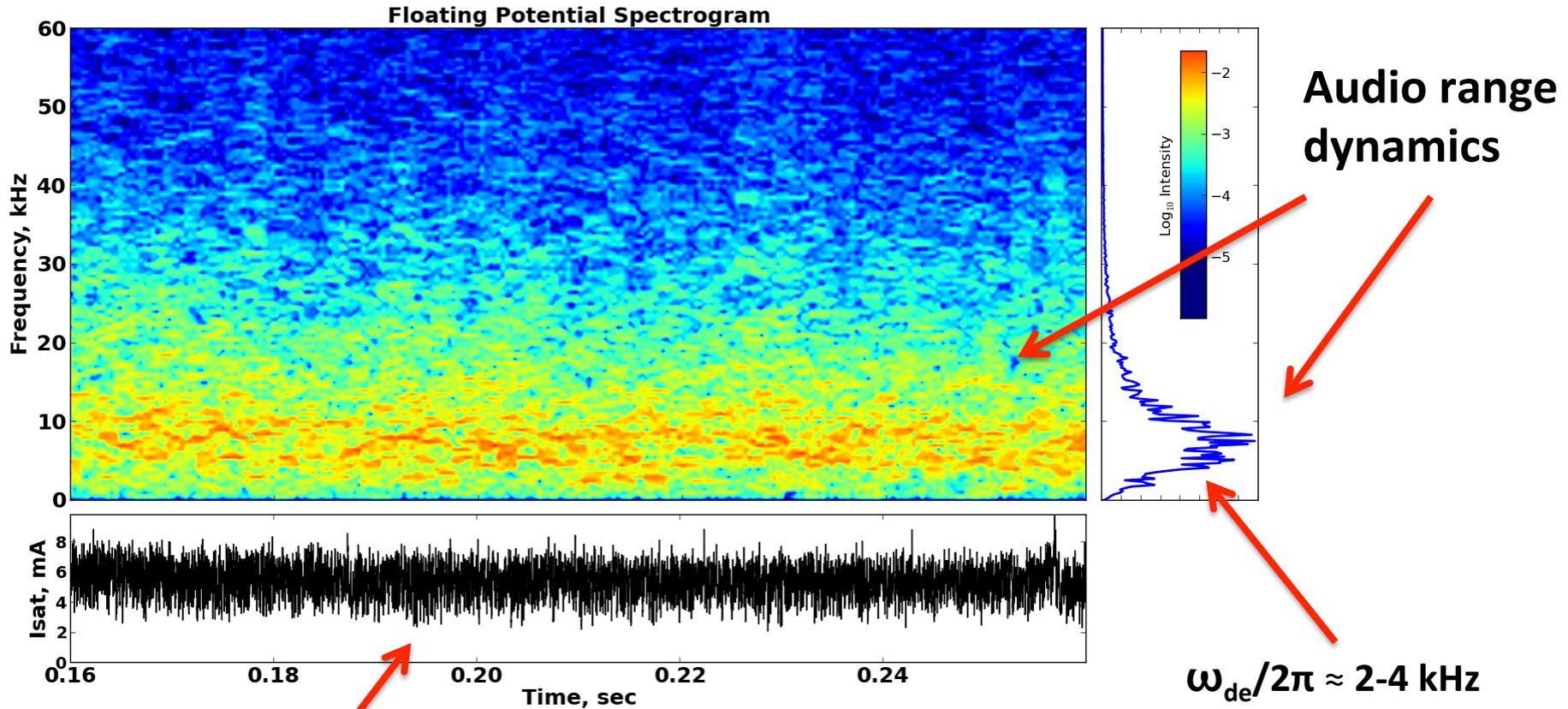
- $T_e = 25-50 \text{ eV} \gg T_i$
- $n \approx 10^{11} \text{ cm}^{-3}$



**Polar
Imaging
Array**

- **96 Gridded Energy Analyzers**
- **8 radii w/ 12 toroidal positions**
- **Biased to collect ions lost to pole**
- **Full-plasma imaging**

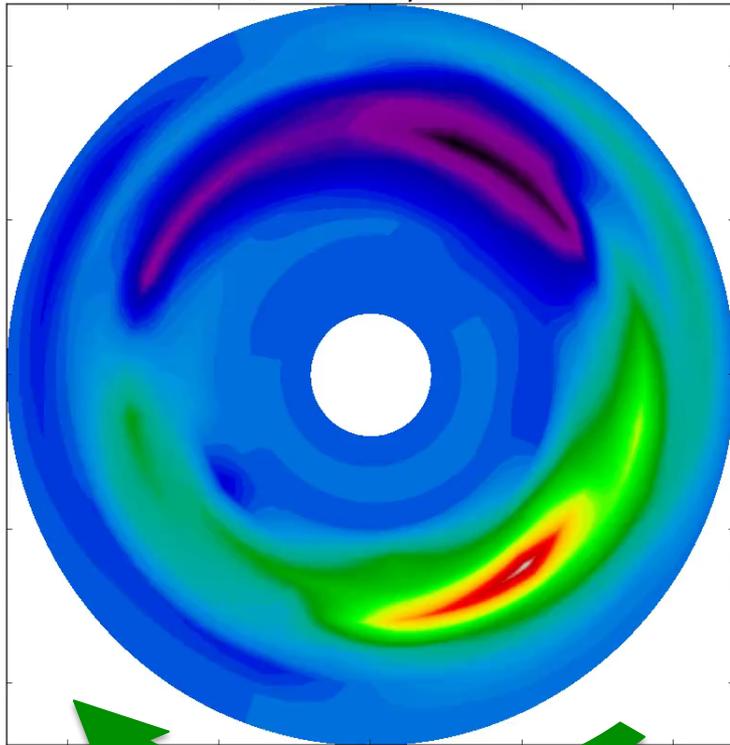
Characteristics of Quasi-Steady Interchange Turbulence



$$\frac{\delta n}{\langle n \rangle} \sim \frac{\delta I_{sat}}{\langle I_{sat} \rangle} \sim \pm 30\% \quad \tilde{V}_{float} \sim \pm 5V$$

Structure of the Turbulence

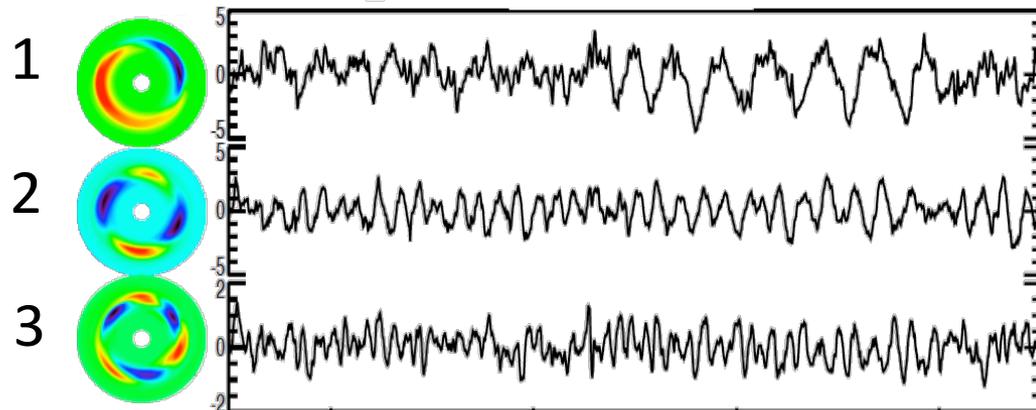
0.420025 seconds, Shot 10047



Electron magnetic drift direction

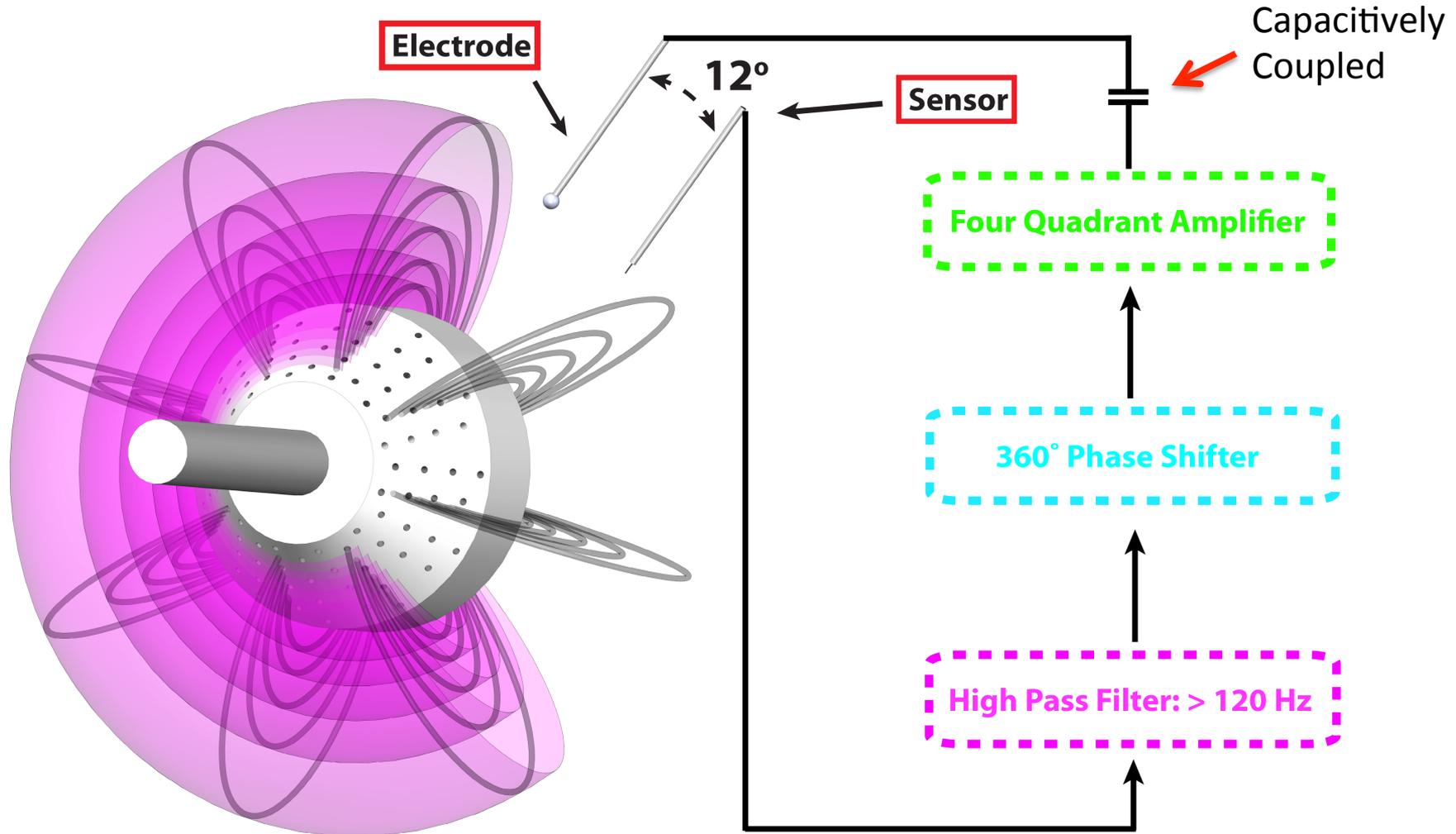
- Radially broad flute-like modes ($k_{\parallel} \approx 0$)
- Low azimuthal mode number, $m = 1, 2, 3$
- Mode rotate with the electron magnetic drift

m Temporal Mode Functions

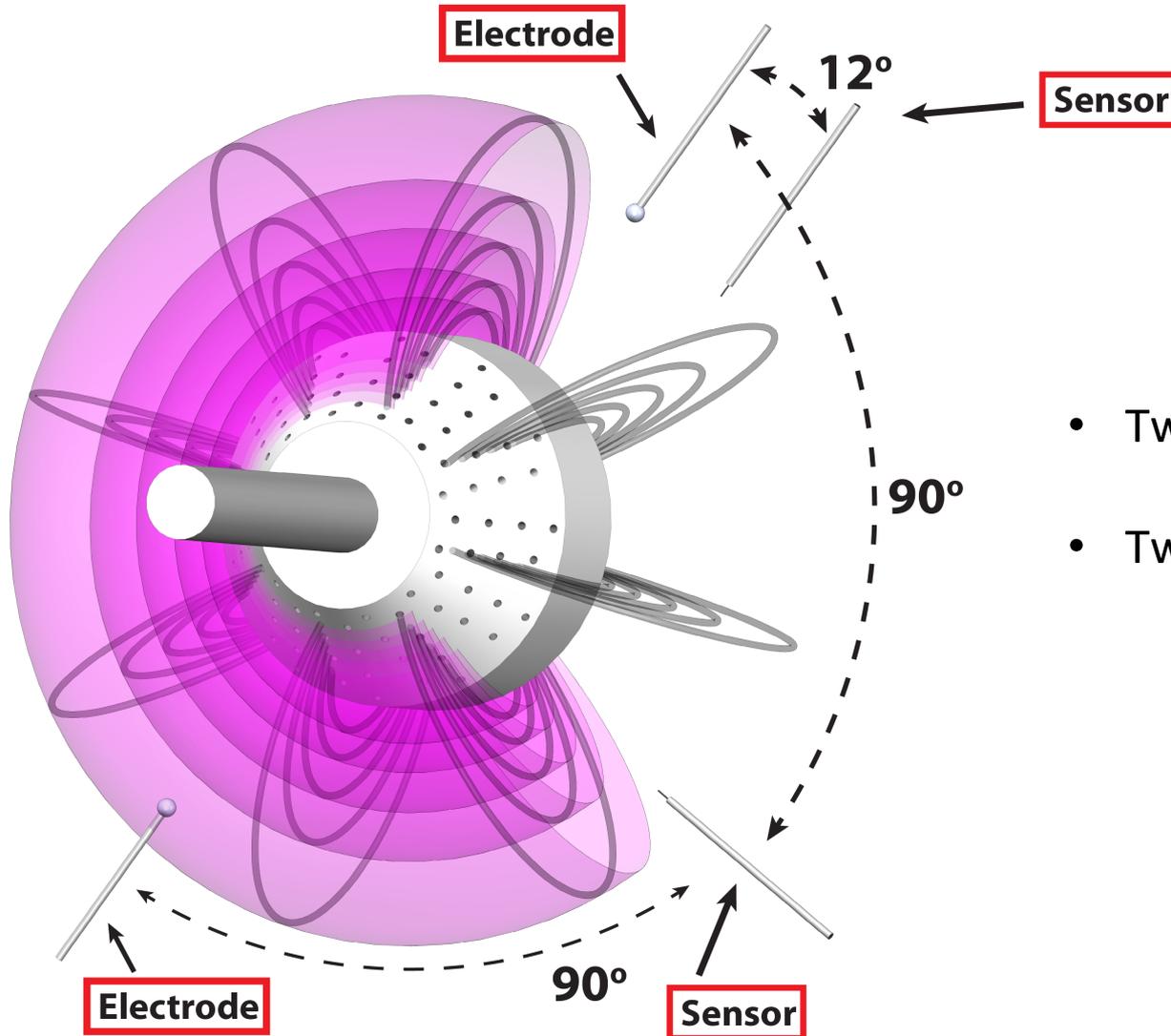


- Chaotically varying amplitude and phase
- Combined correlation length of 50-75°

Current-Collection Feedback



Current-Collection Feedback

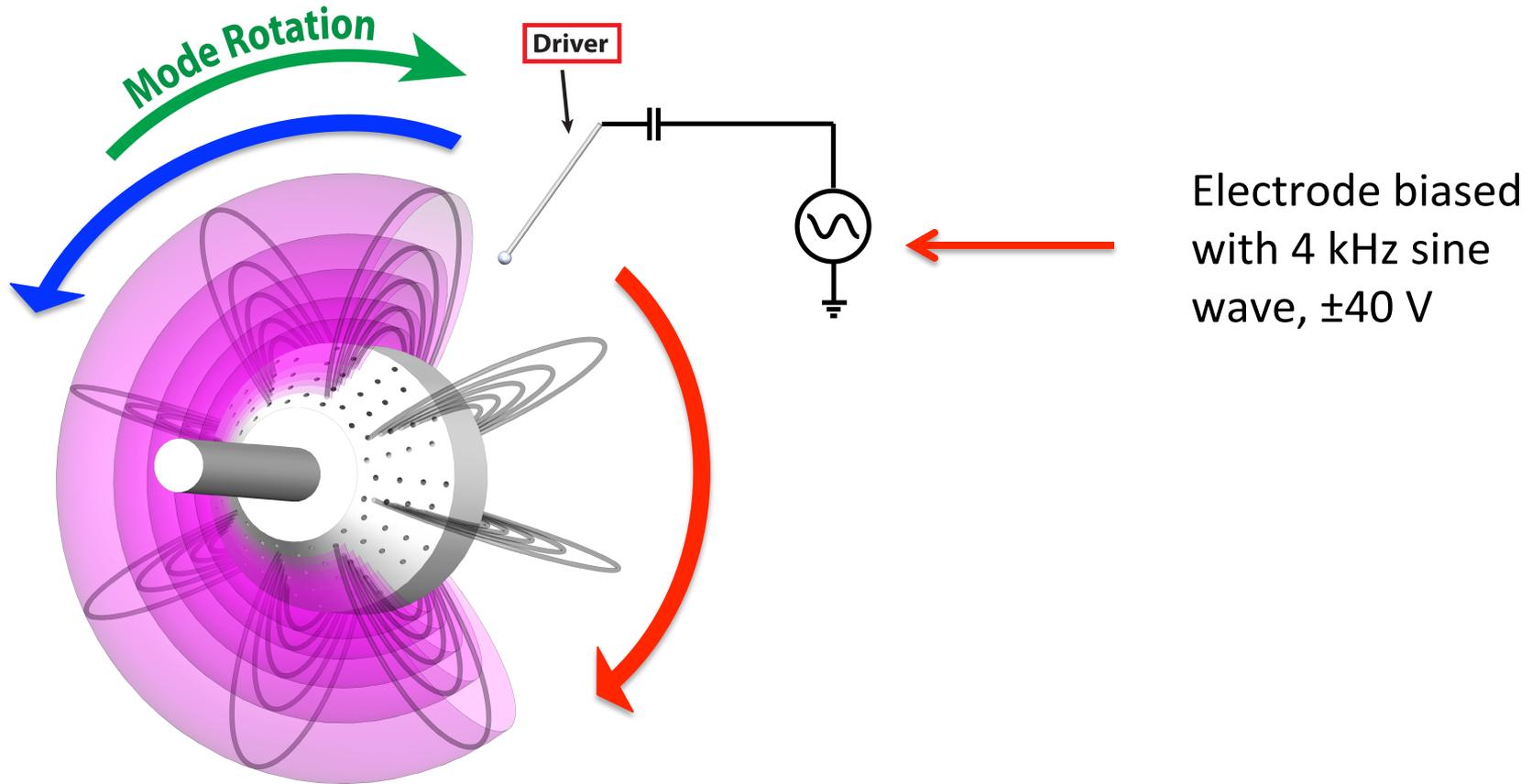


- Two sensor locations
- Two electrode locations

- Feedback on **Interchange** Modes
 - Prater applied narrow-band feedback with a biasing electrode to suppress large growth rate flute modes.
(R. Prater, *Phys. Rev. Lett.* **27**, 132 – July 1971)
- Feedback in **Turbulent** Plasmas
 - TEXT group used biasing electrodes to suppress broadband drift wave turbulence in tokamak edge.
(B. Richards, *Phys. Plasmas* **1**, 1606 (1994))
(T. Uckan, *Nucl. Fusion* 35 487 (1995))
- The feedback in CTX is different from both of the above cases:
 - **Broadband** feedback is applied to global **interchange** turbulence in the magnetospheric configuration.

- 1. Plasma responds to coherent current-collection (feedforward)**
2. Triggering feedback on and off shows amplification and suppression of fluctuations and a localized effect.
3. Varying the gain and phase of the current relative to the floating potential significantly changes the spectrum.
4. Varying the separation between the sensor and electrode shows the effect of decorrelation on feedback influence.

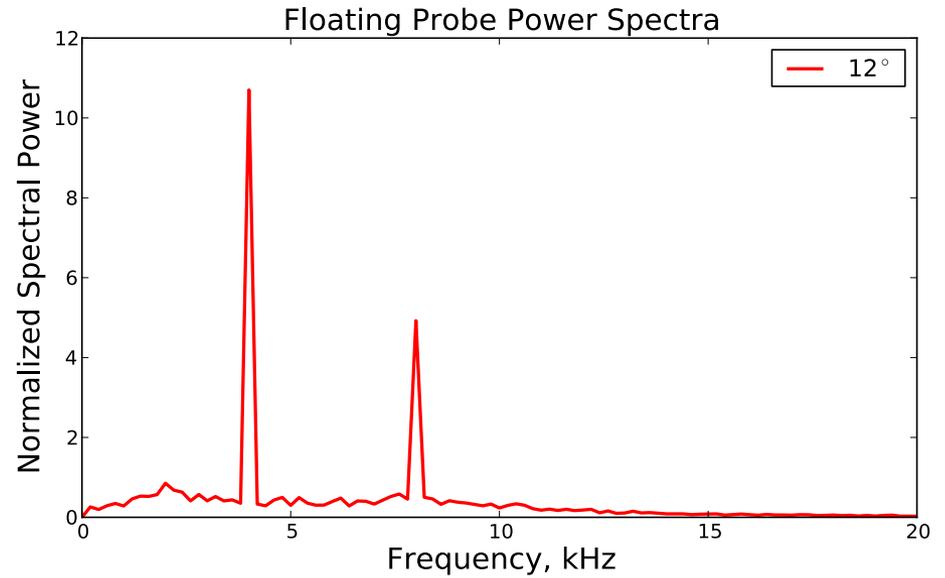
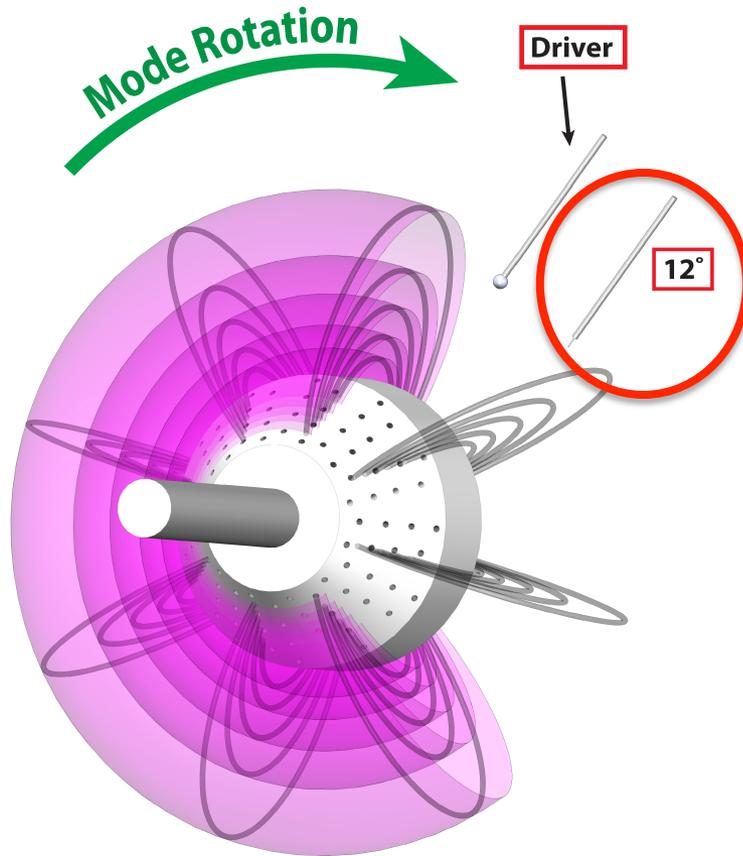
Driving a Coherent Current Oscillation



Downstream: Plasma has moved past electrode

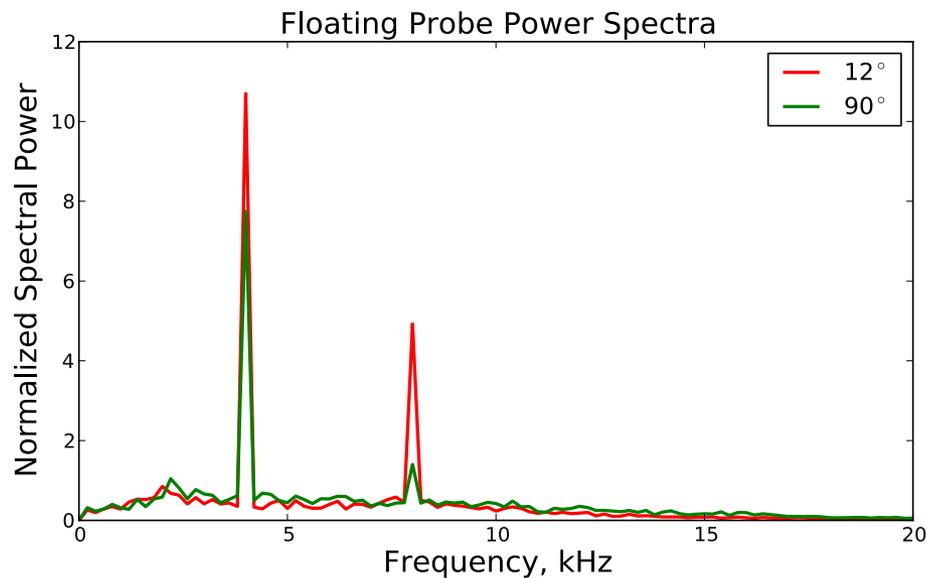
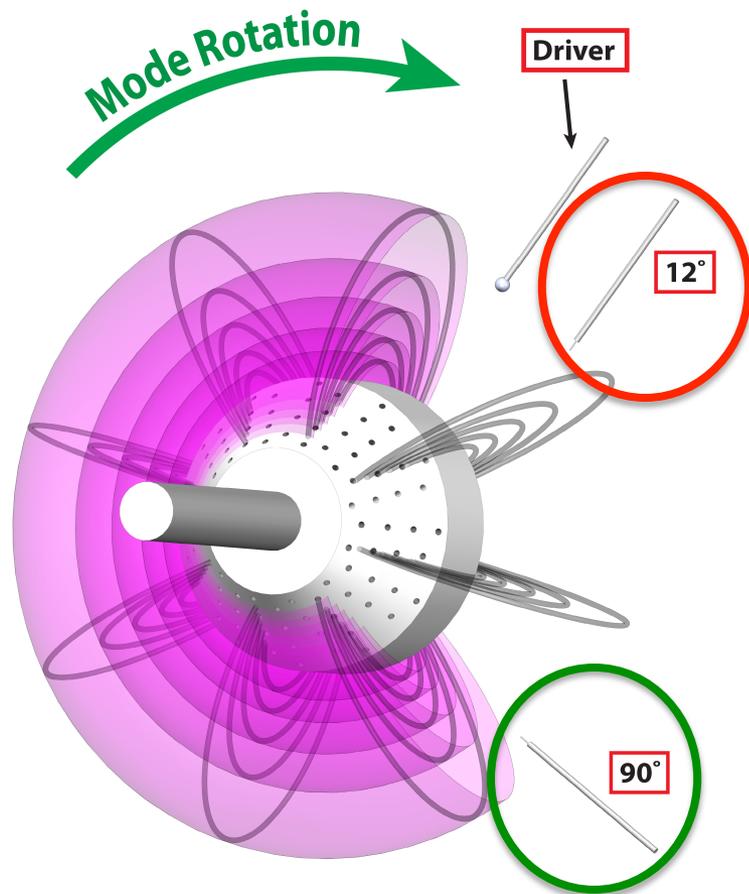
Upstream: Plasma has yet to move past electrode

Driving a Coherent Current Oscillation



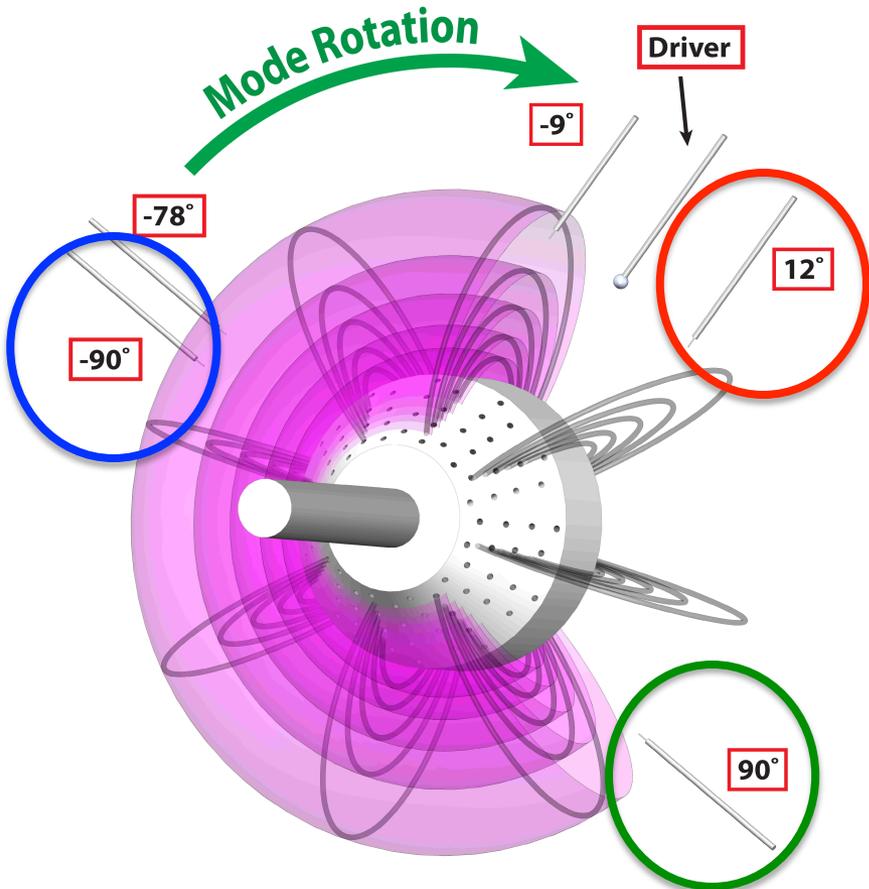
- Electrode biased with 4 kHz sine wave, ± 40 V

Driving a Coherent Current Oscillation

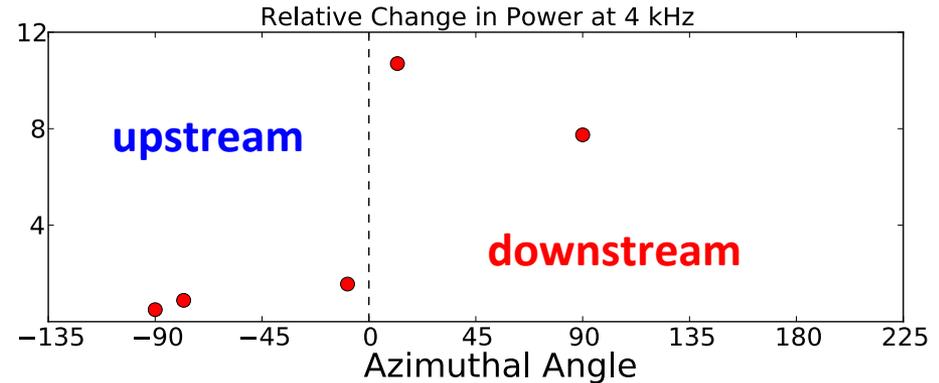
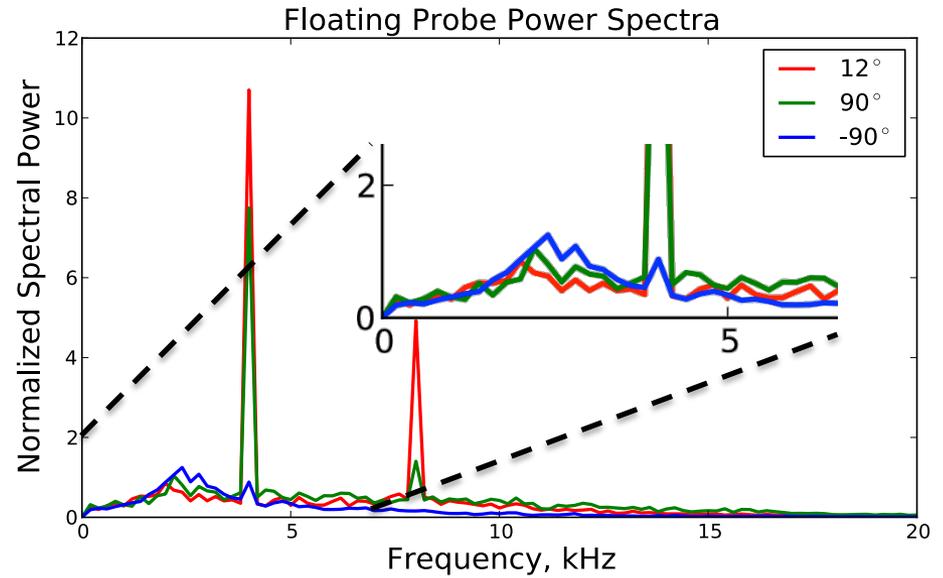


- Electrode biased with 4 kHz sine wave, ± 40 V

Driving a Coherent Current Oscillation



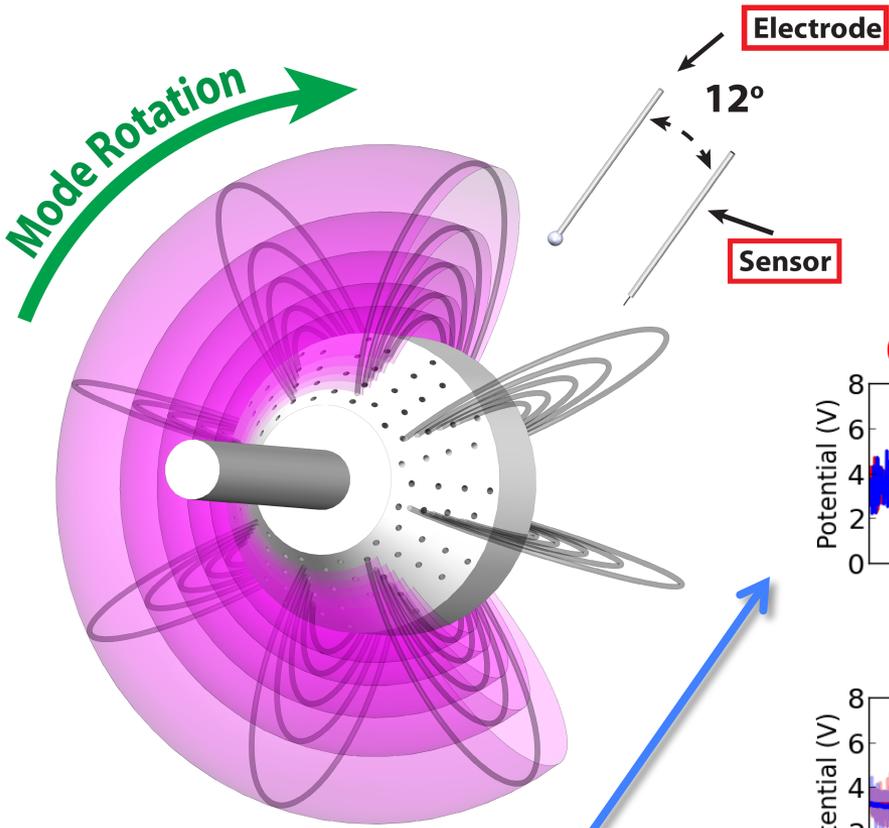
- Electrode biased with 4 kHz sine wave, ± 40 V
- Launches coherent wave in direction of mode rotation
- Downstream influence significantly greater



Mode Rotation

1. Plasma responds to coherent current-collection (feedforward)
- 2. Triggering feedback on and off shows amplification and suppression of fluctuations and a localized effect.**
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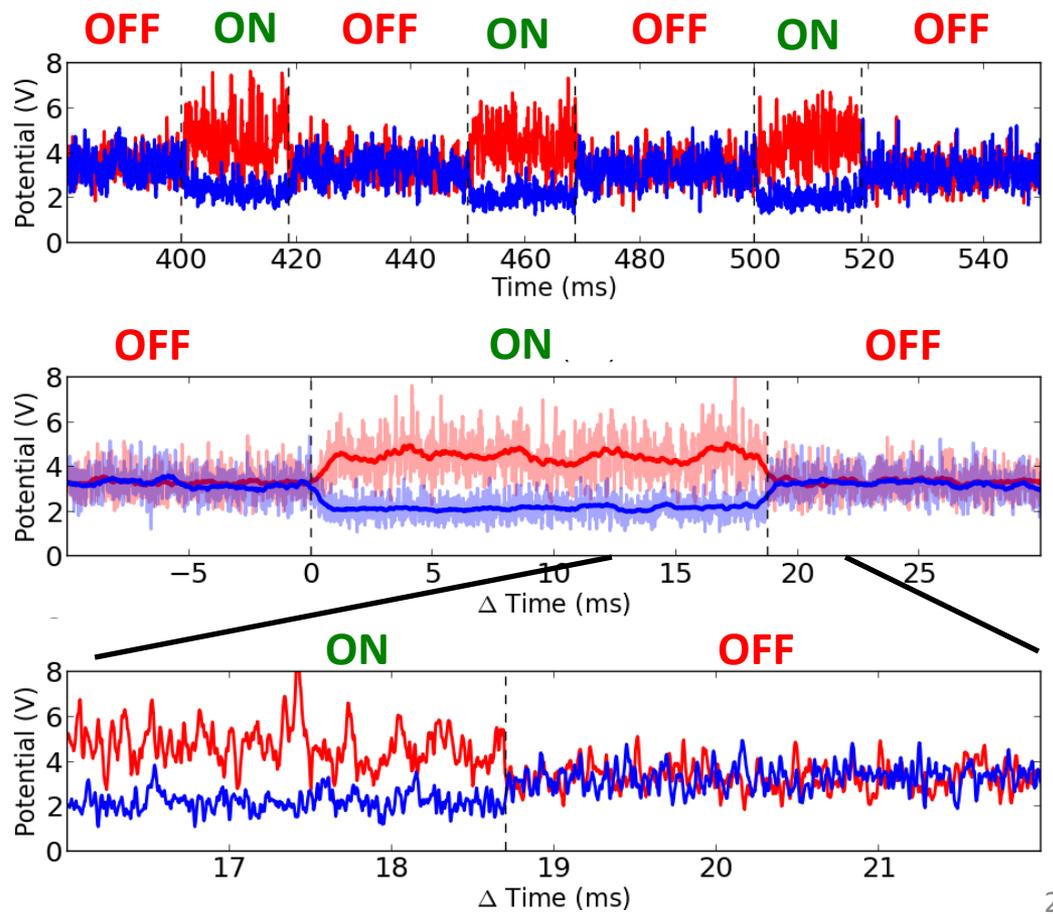
Triggered Feedback Show Amplification and Suppression



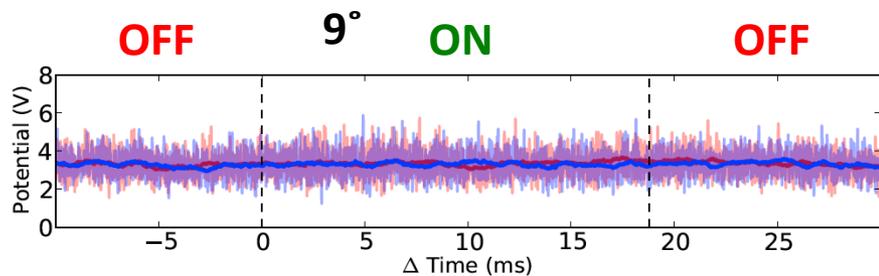
- $G = \pm 4$
- **Amplification** $\rightarrow +30\%$
- **Suppression** $\rightarrow -30\%$
- Relaxation time $< 20 \mu s$

Moving RMS Fluctuations of Floating Potential

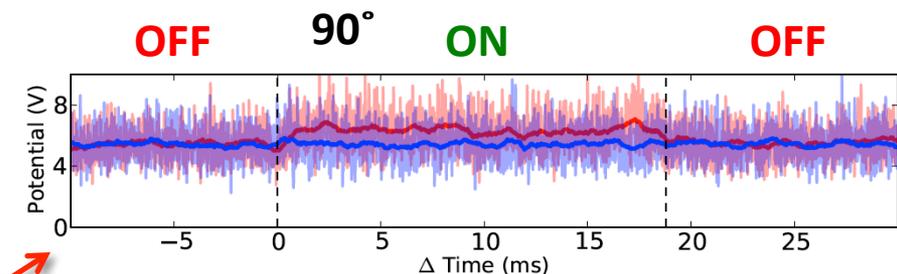
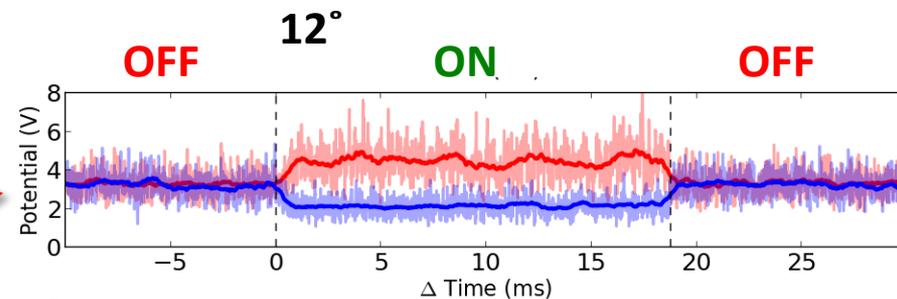
Averaging of triggering events



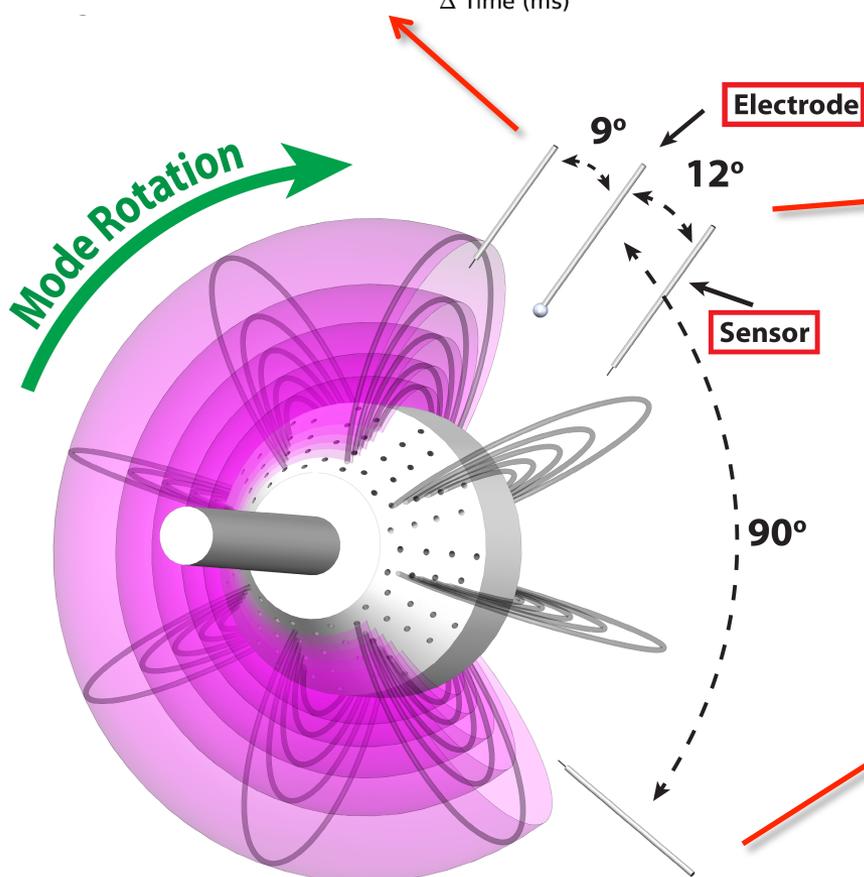
Influence Diminishes with Azimuthal Separation



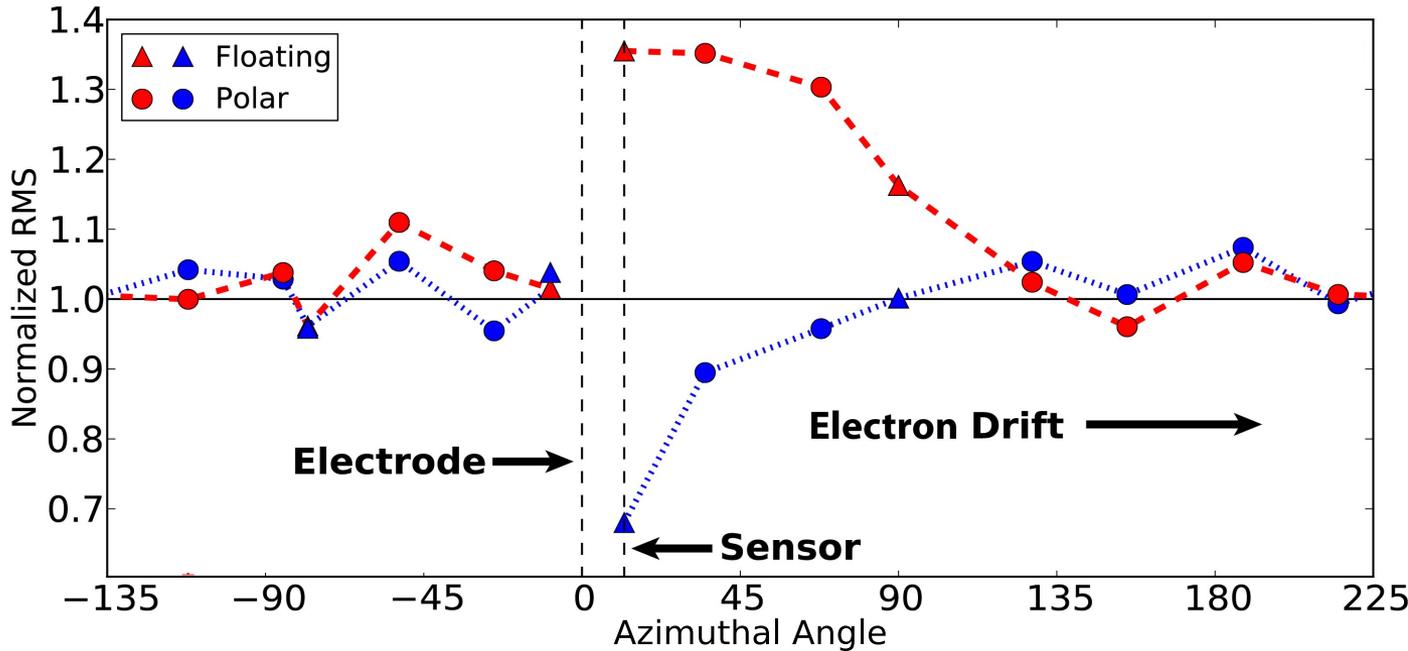
Nearby “upstream” probe sees no response



“Downstream” probe sees reduced response

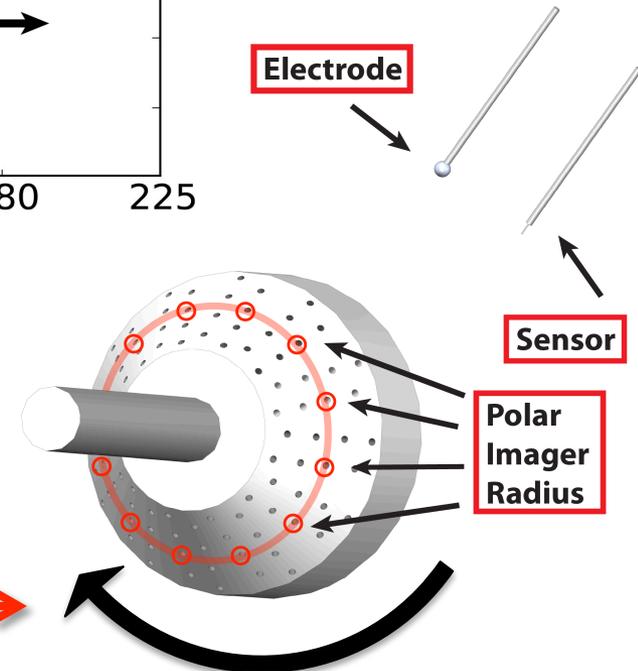


Influence of Feedback is Spatially Localized

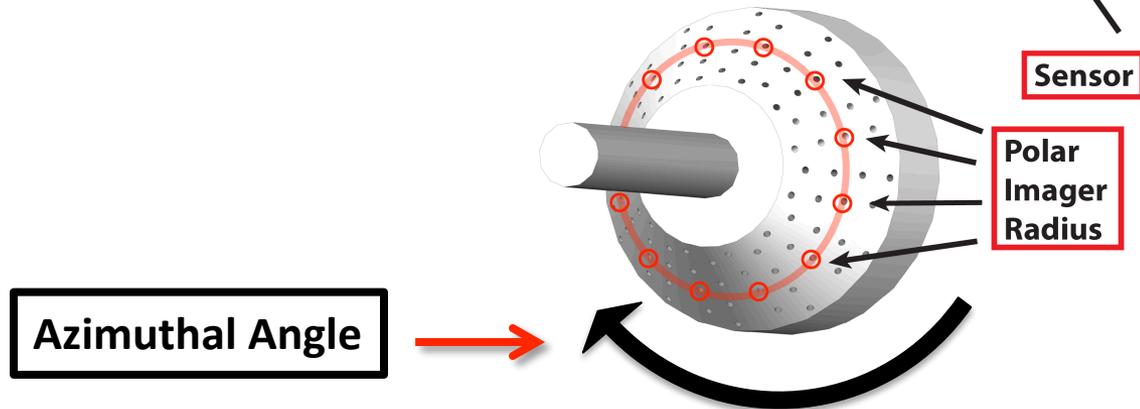
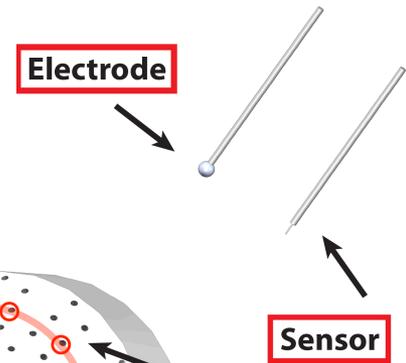
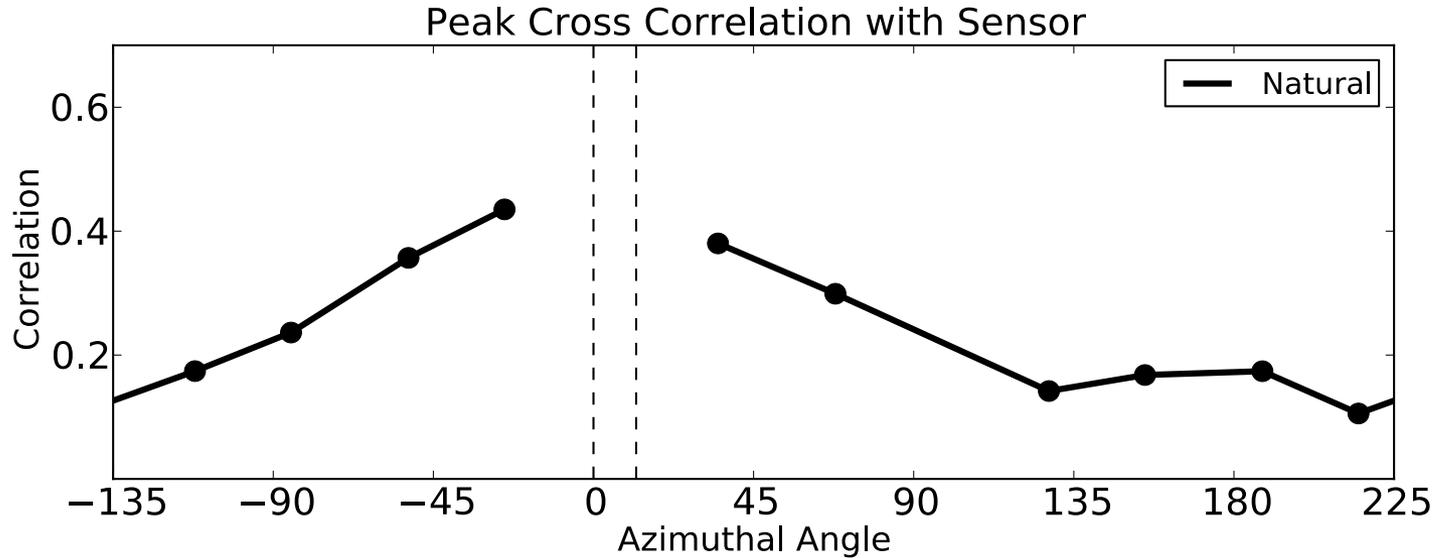


- RMS normalized to “natural” values
- No influence in the direction opposite to mode rotation

Azimuthal Angle →

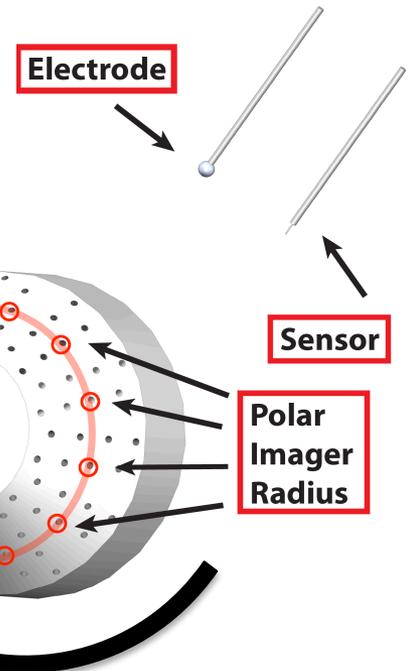
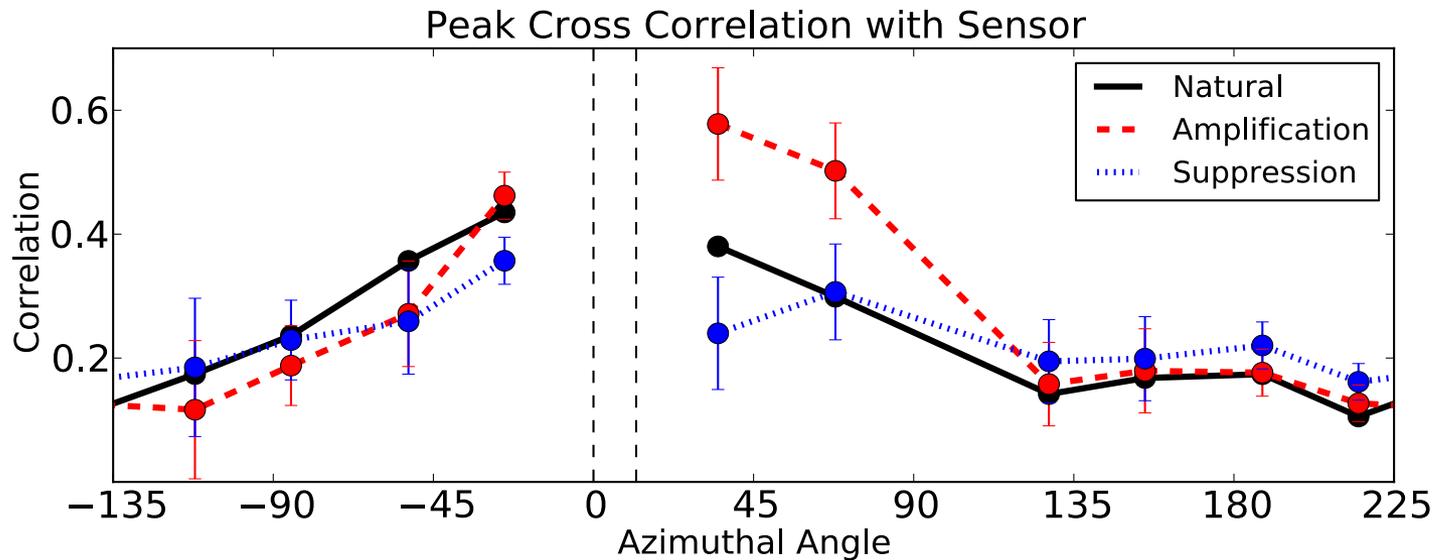


Feedback Increases or Decreases Correlation



Feedback Increases or Decreases Correlation

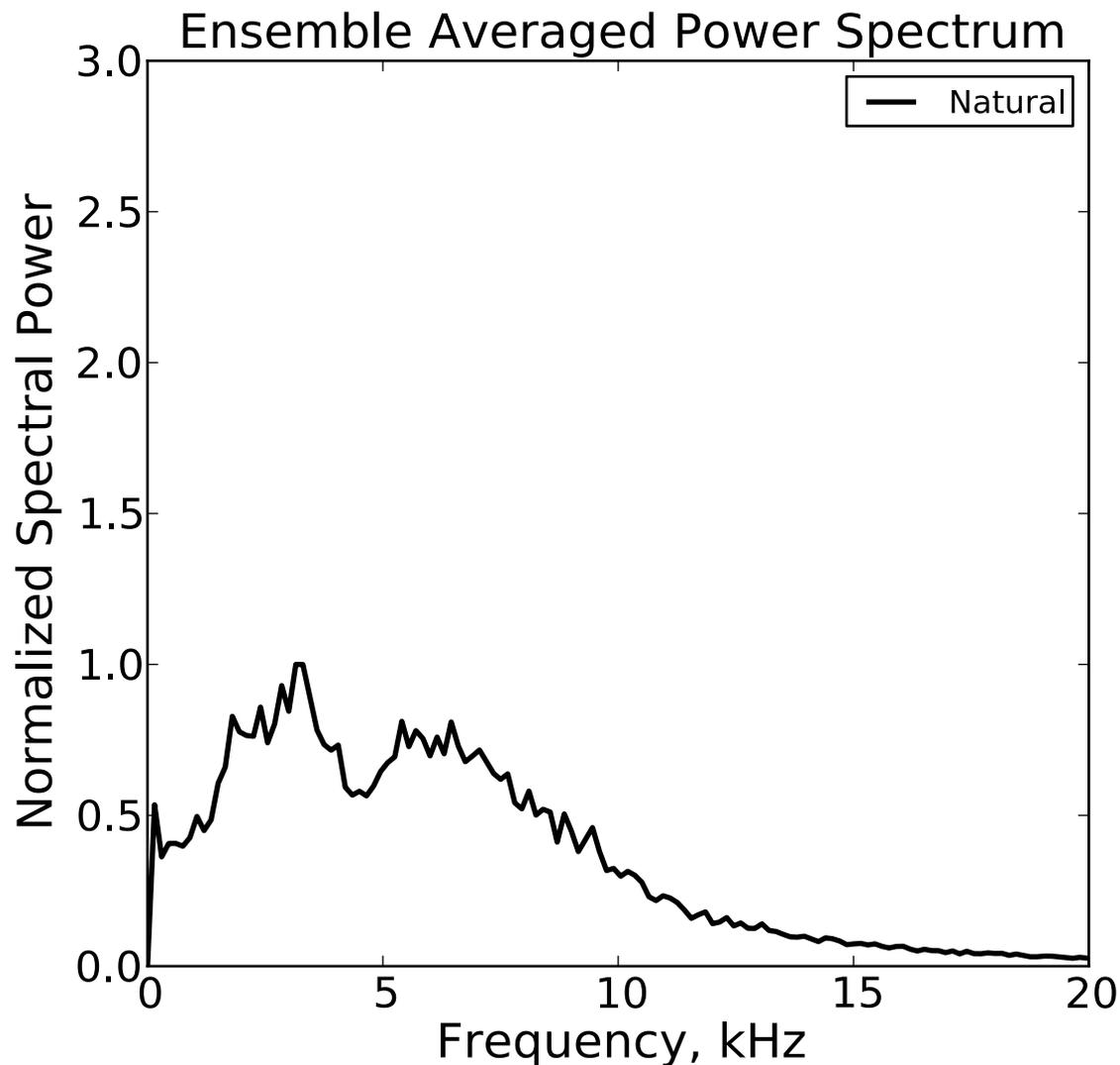
Correlation **stronger** with **positive** feedback, **reduced** with **negative** feedback



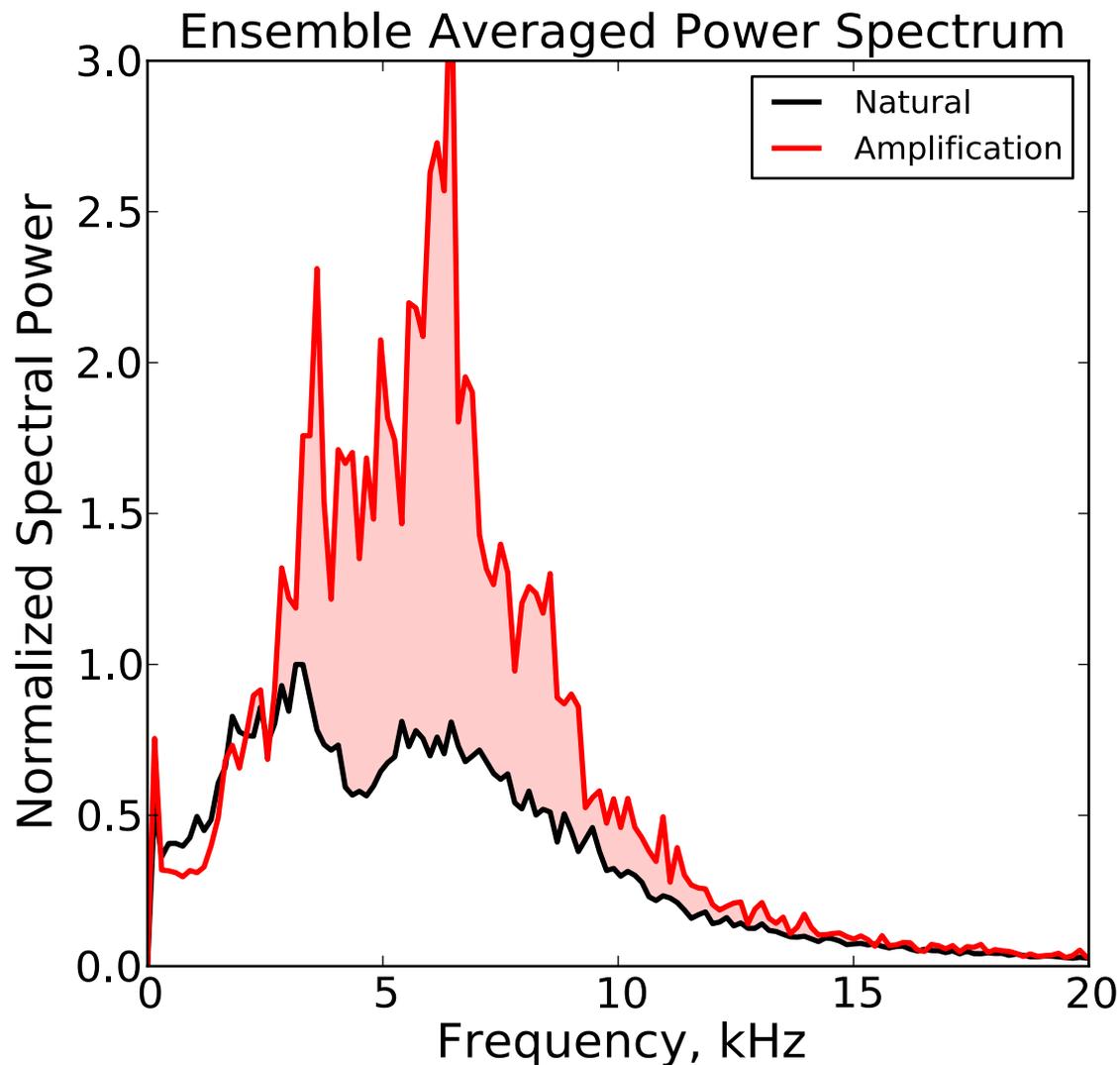
Azimuthal Angle

1. Plasma responds to coherent current-collection (feedforward)
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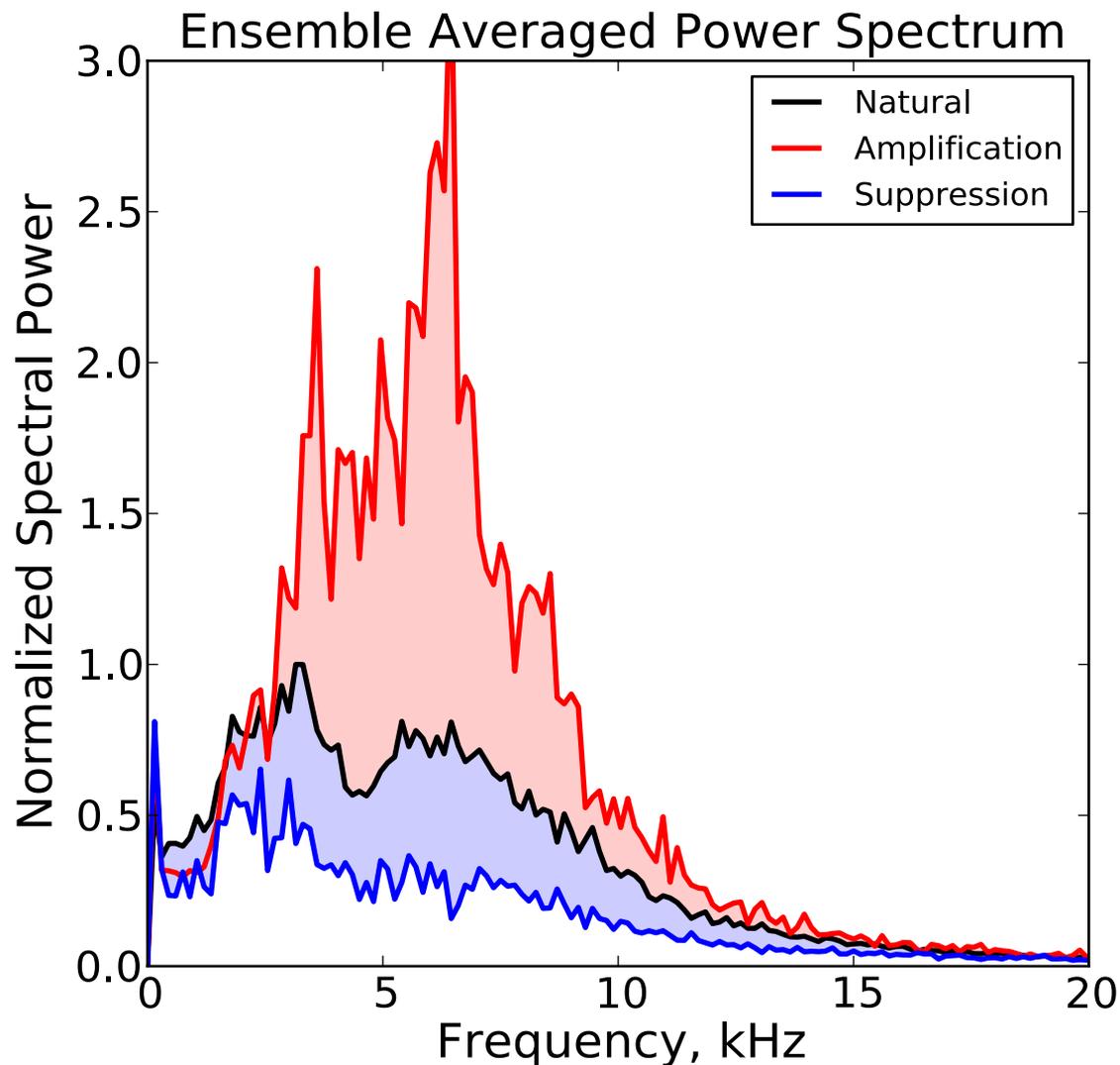
Turbulent Spectrum Shows Influence of Feedback



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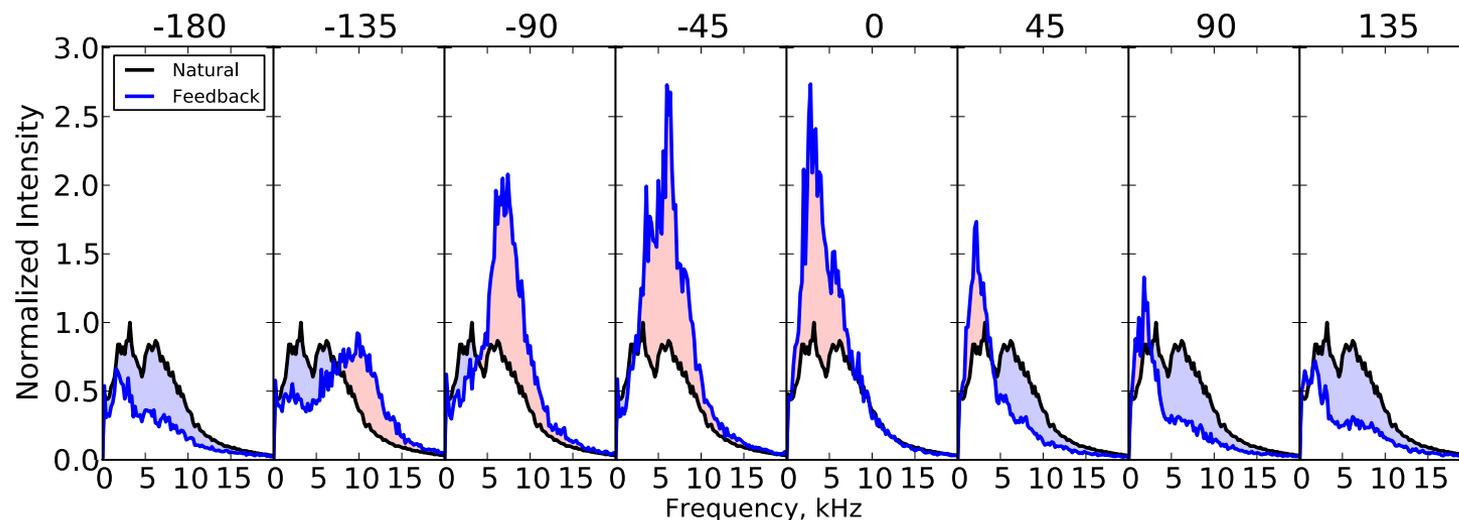
Turbulent Spectrum Shows Influence of Feedback



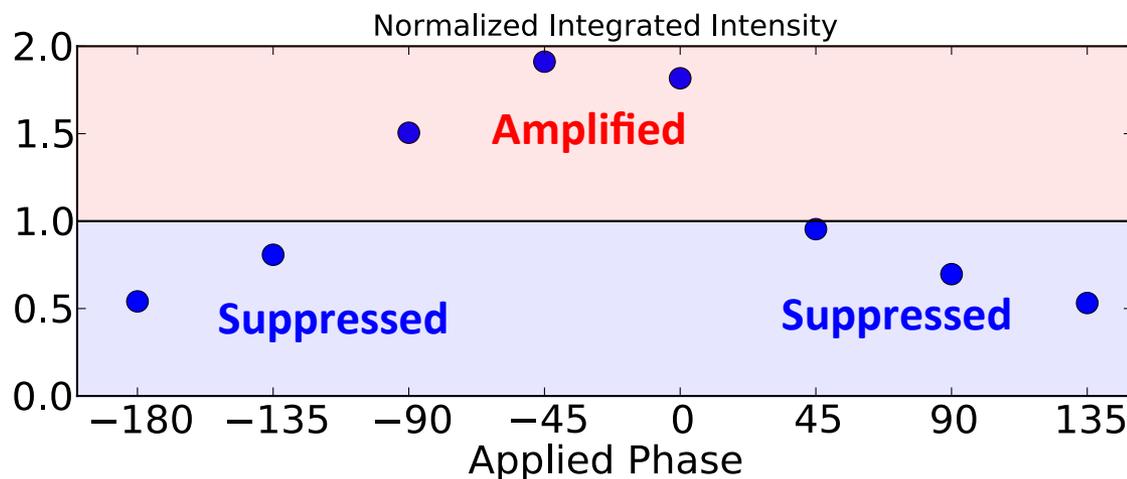
Changing Turbulent Spectrum with Phase



Fixed gain of 4



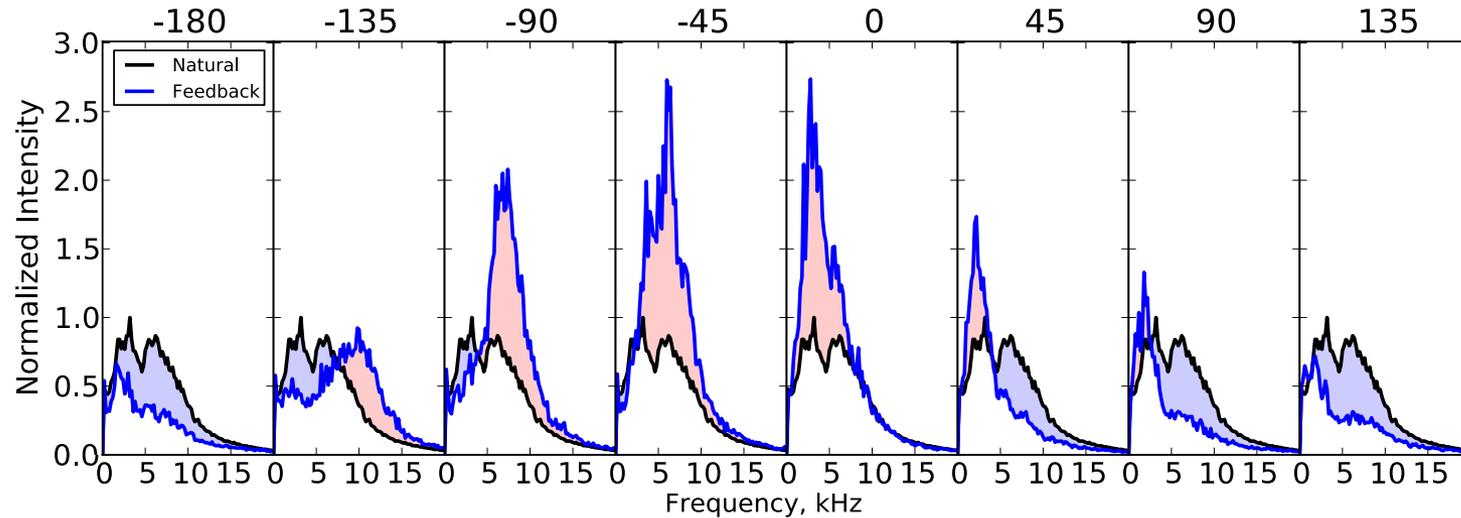
Band Integrated (1-10 kHz)
Spectral Intensity



Changing Turbulent Spectrum with Phase

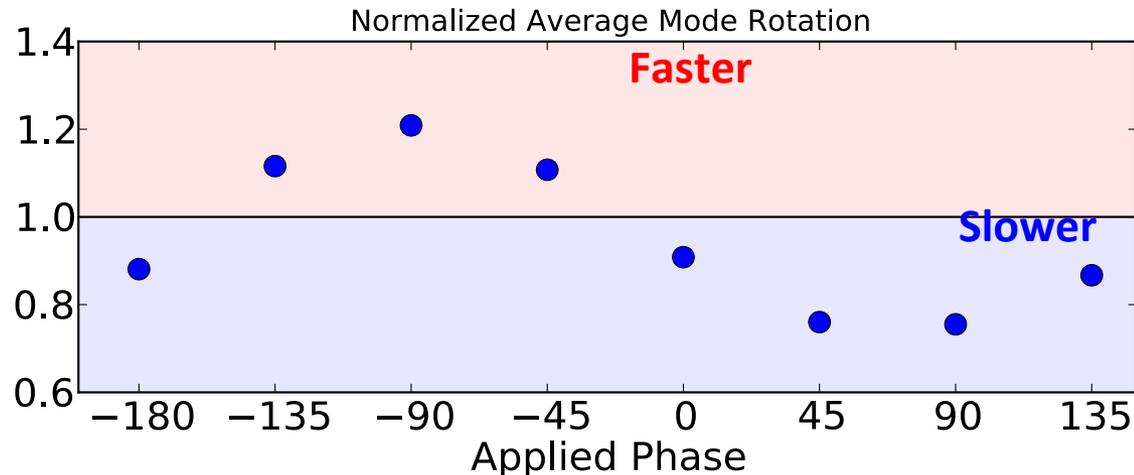


Fixed gain of 4

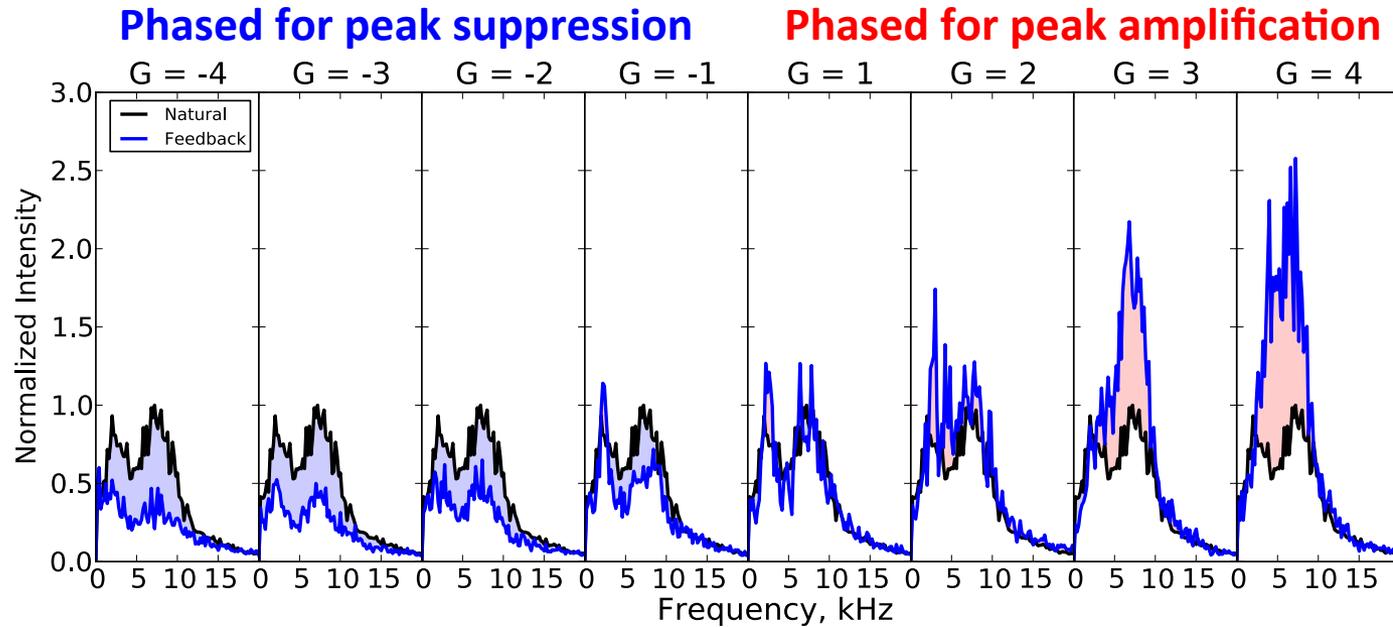


Frequency of amplified modes changes with phase

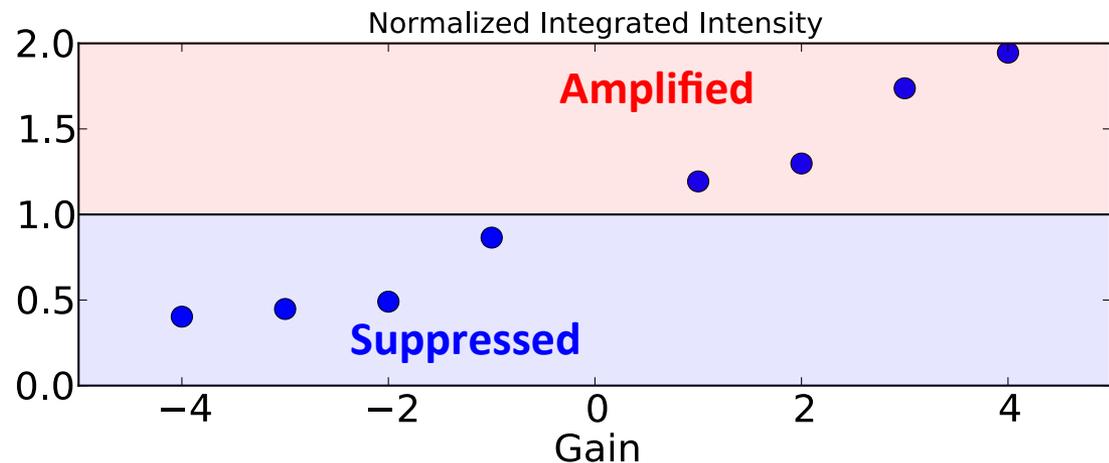
Intensity Weighted Frequency (1-10 kHz)



Gain Scan: +G -> Amplification, -G -> Suppression



Band Integrated (1-10 kHz)
Spectral Intensity



Defining Power and Conductance

Time Average Power

$$\langle P \rangle \equiv \frac{1}{T} \int_0^T I(t) \tilde{V}_P(t) dt$$

$$\langle P \rangle > 0 \quad \text{Power into plasma}$$

$$\langle P \rangle < 0 \quad \text{Power out of plasma}$$

← Like the magnetosphere!

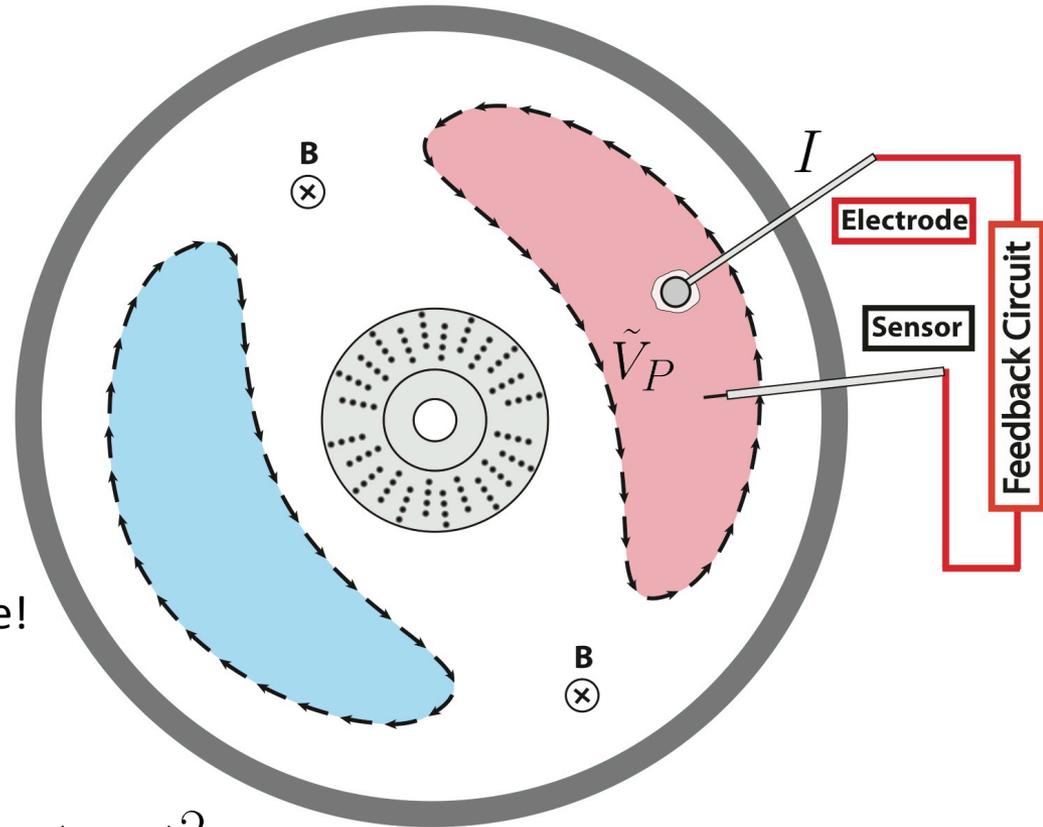
Spectral Power Flow: Conductance

$$\tilde{V}_P(\omega)^* I(\omega) = \tilde{V}_P^*(Y \tilde{V}_P) = Y |V_P|^2$$

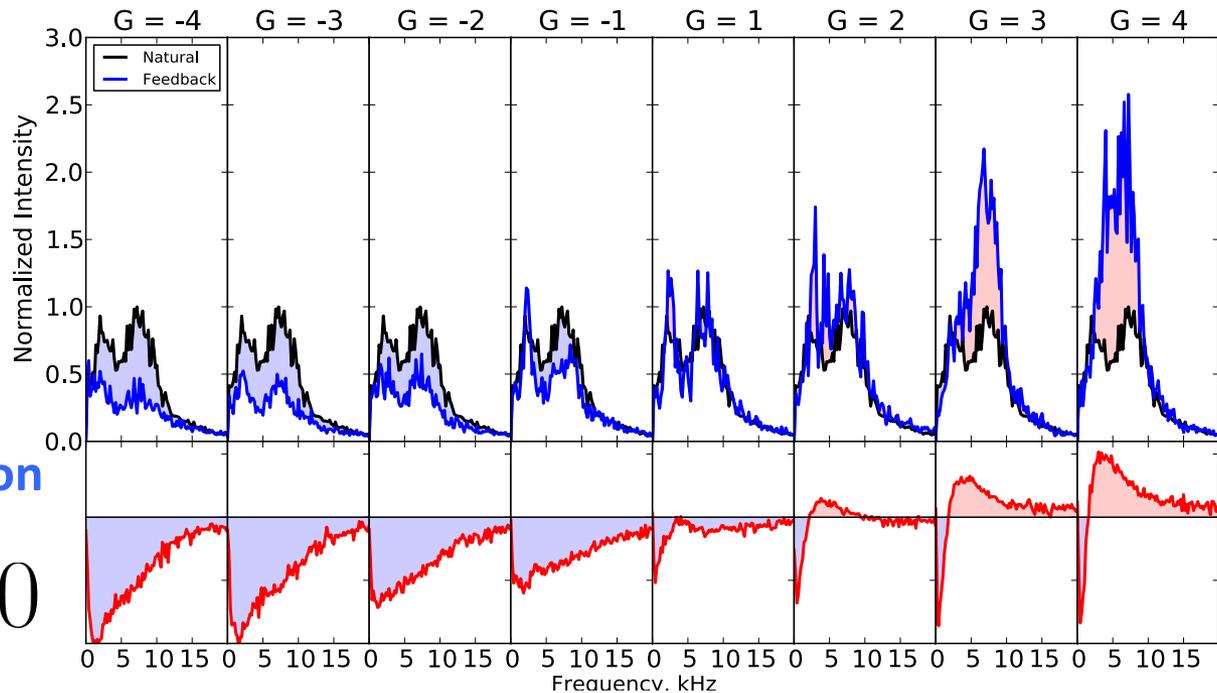
$$\text{Admittance} \quad Y = \frac{\tilde{V}_P^* I}{|V_P|^2}$$

$$\sigma = \text{Re} \left(\frac{\tilde{V}_s^* I}{|\tilde{V}_s|^2} \right)$$

Conductance



Sign of Conductance Determines Power Flow



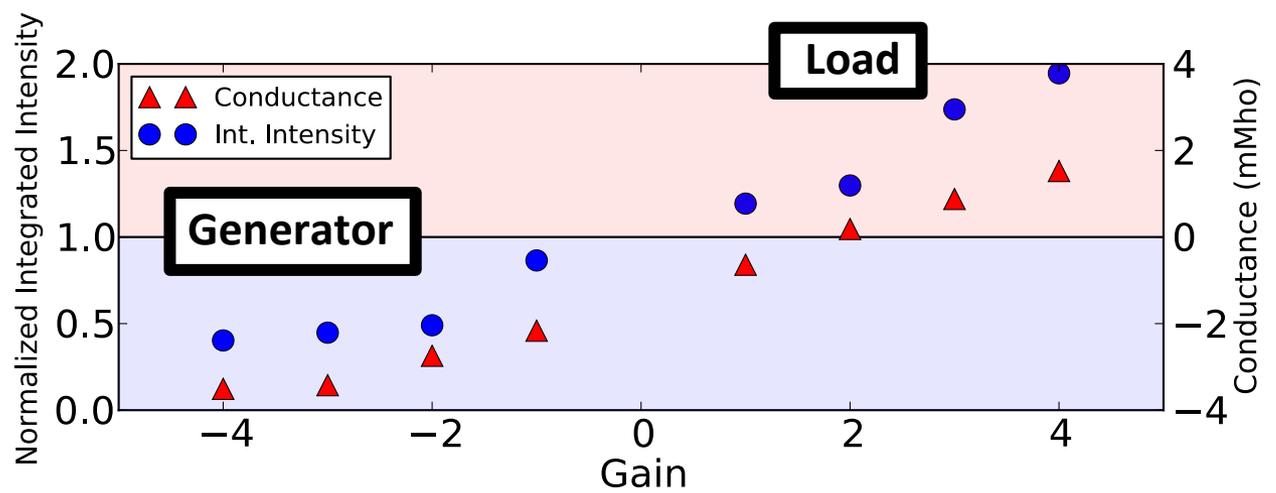
$$\sigma = \text{Re} \left(\frac{\tilde{V}_s^* I}{|\tilde{V}_s|^2} \right)$$

Suppression
where $\sigma < 0$

Amplification
where $\sigma > 0$

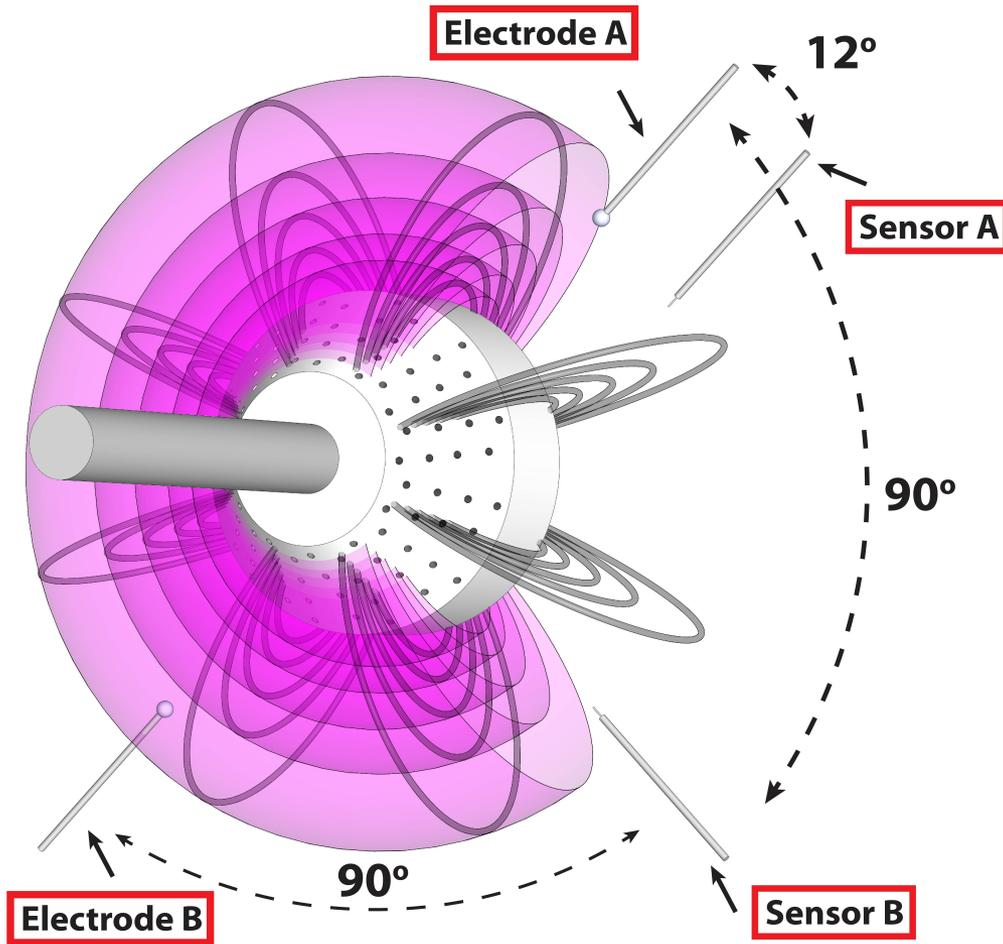
Band Integrated (1-10 kHz)
Spectral Intensity

Band Averaged (1-10 kHz)
Conductance



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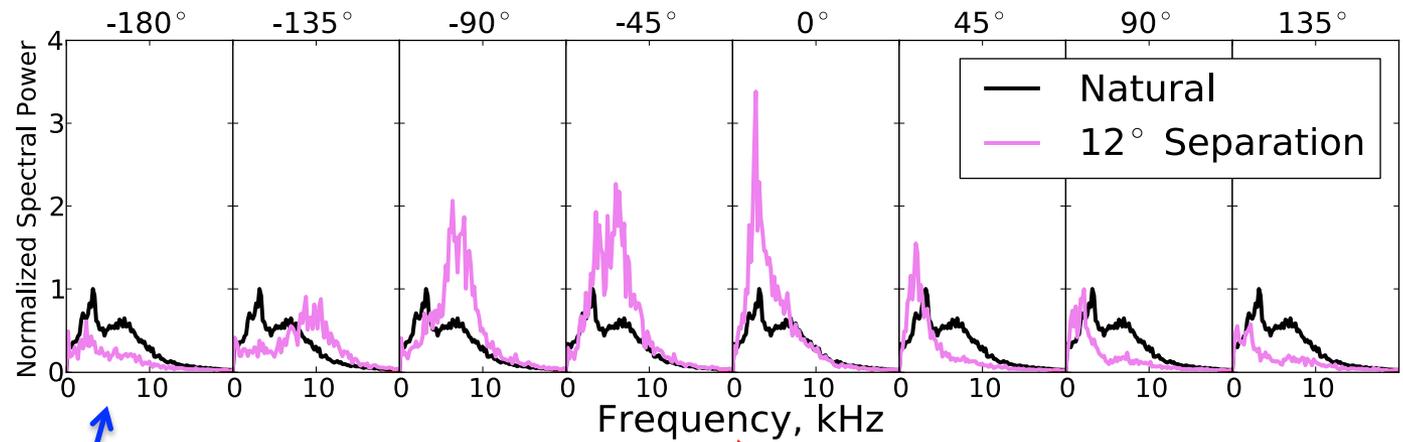
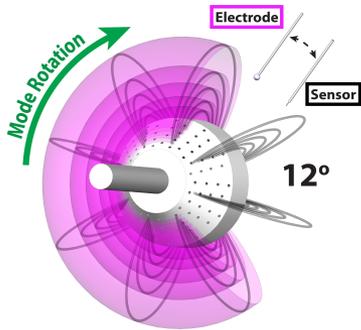
Varying the Separation between the Sensor and Electrode



Adjust the toroidal separation

- Reposition sensor/electrodes
- Reverse mode direction

Varying the Separation between the Sensor and Electrode

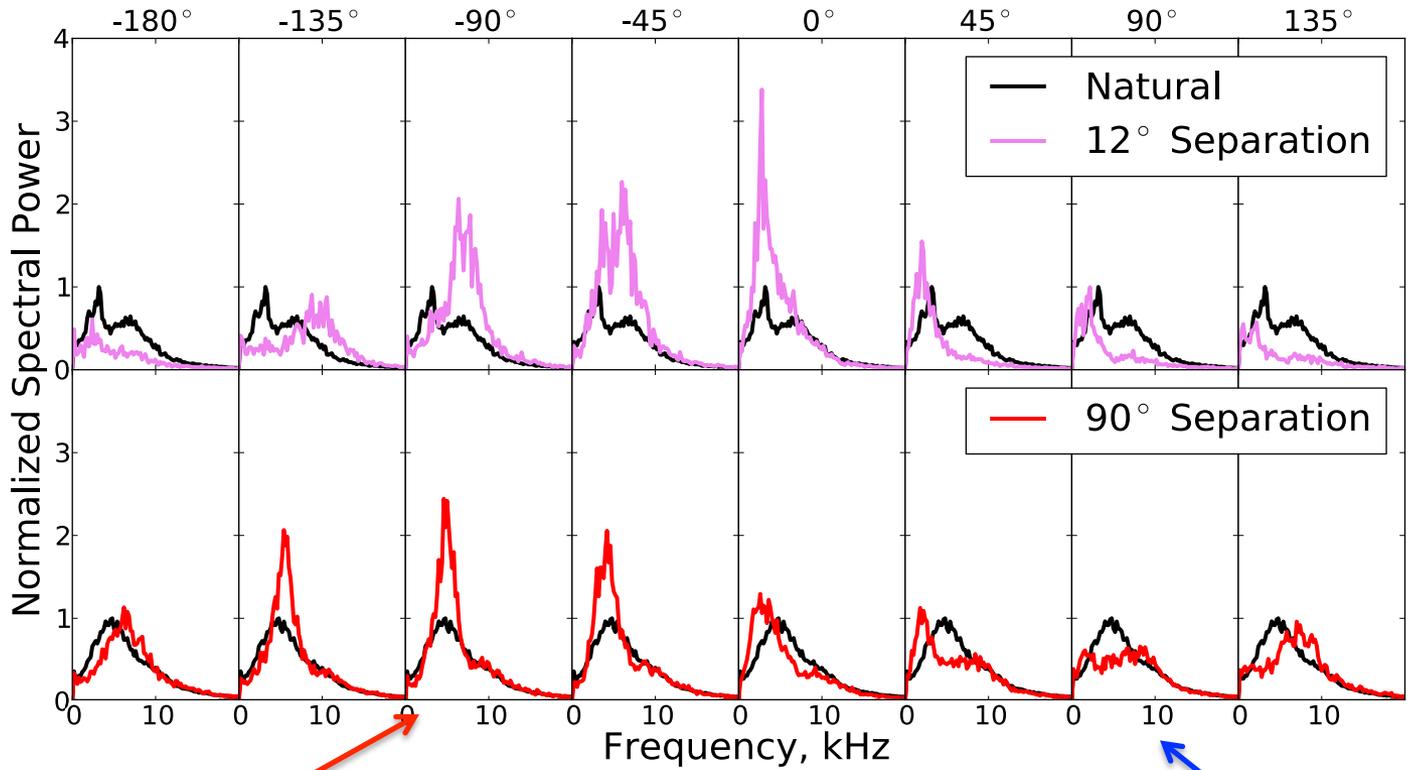
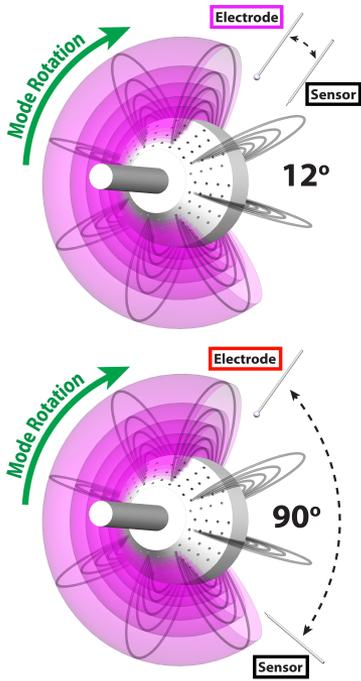


peak suppression

peak amplification

- Fixed gain of 4
- Electrode **leading** the sensor

Varying the Separation between the Sensor and Electrode

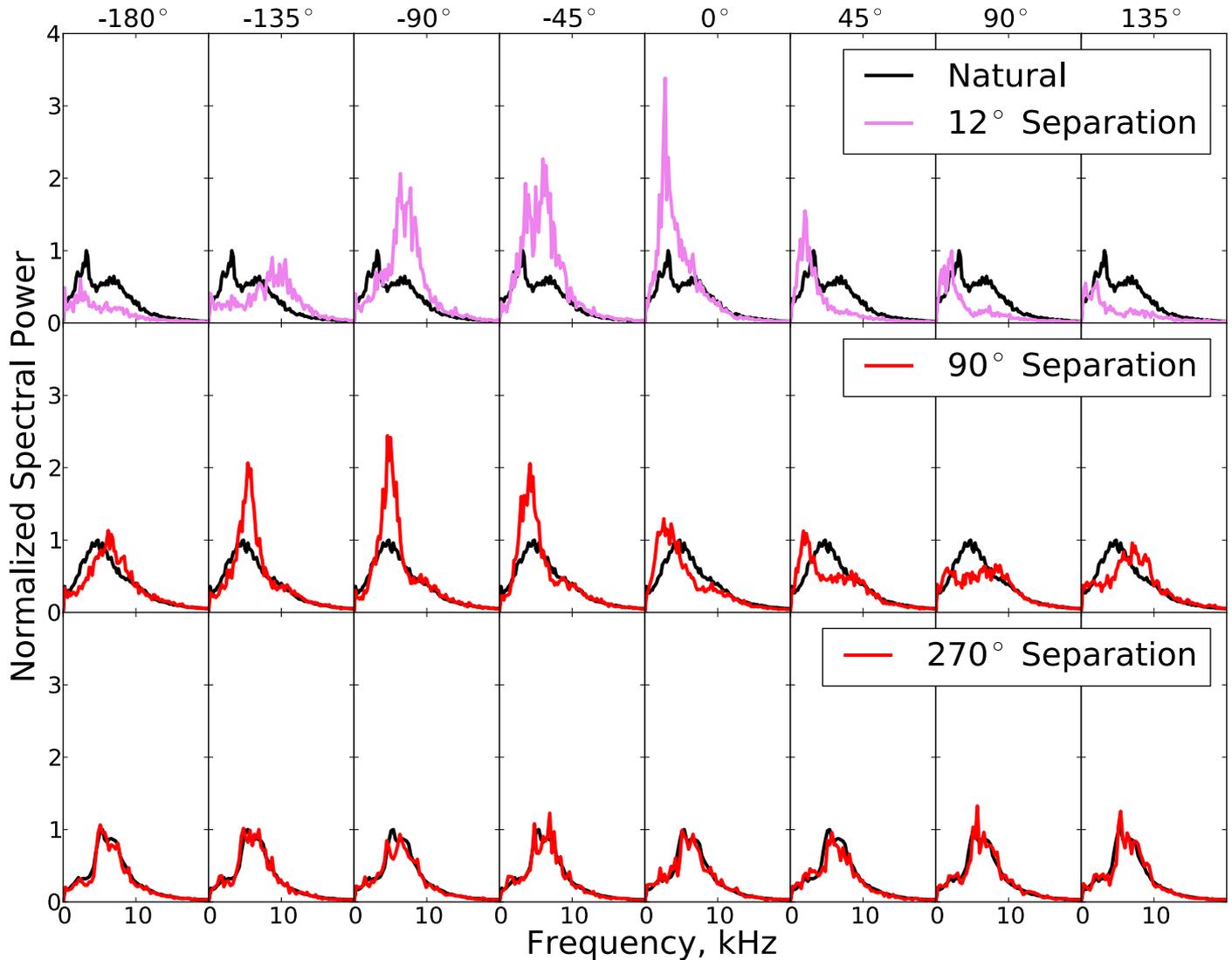
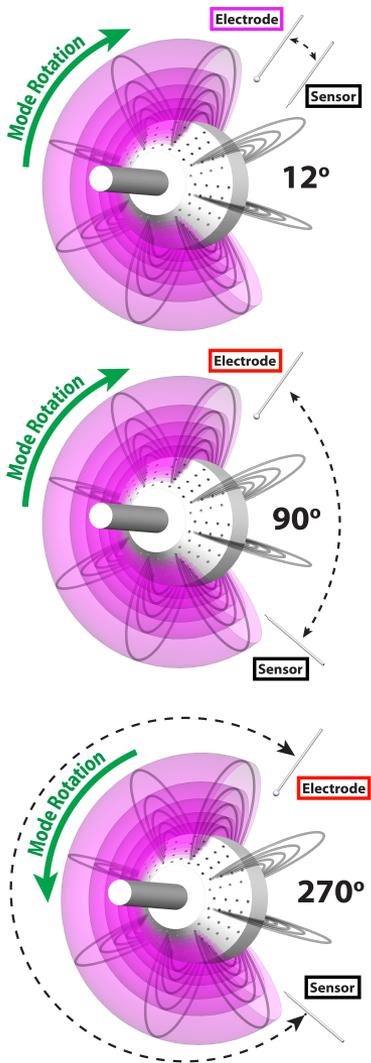


peak amplification

peak suppression

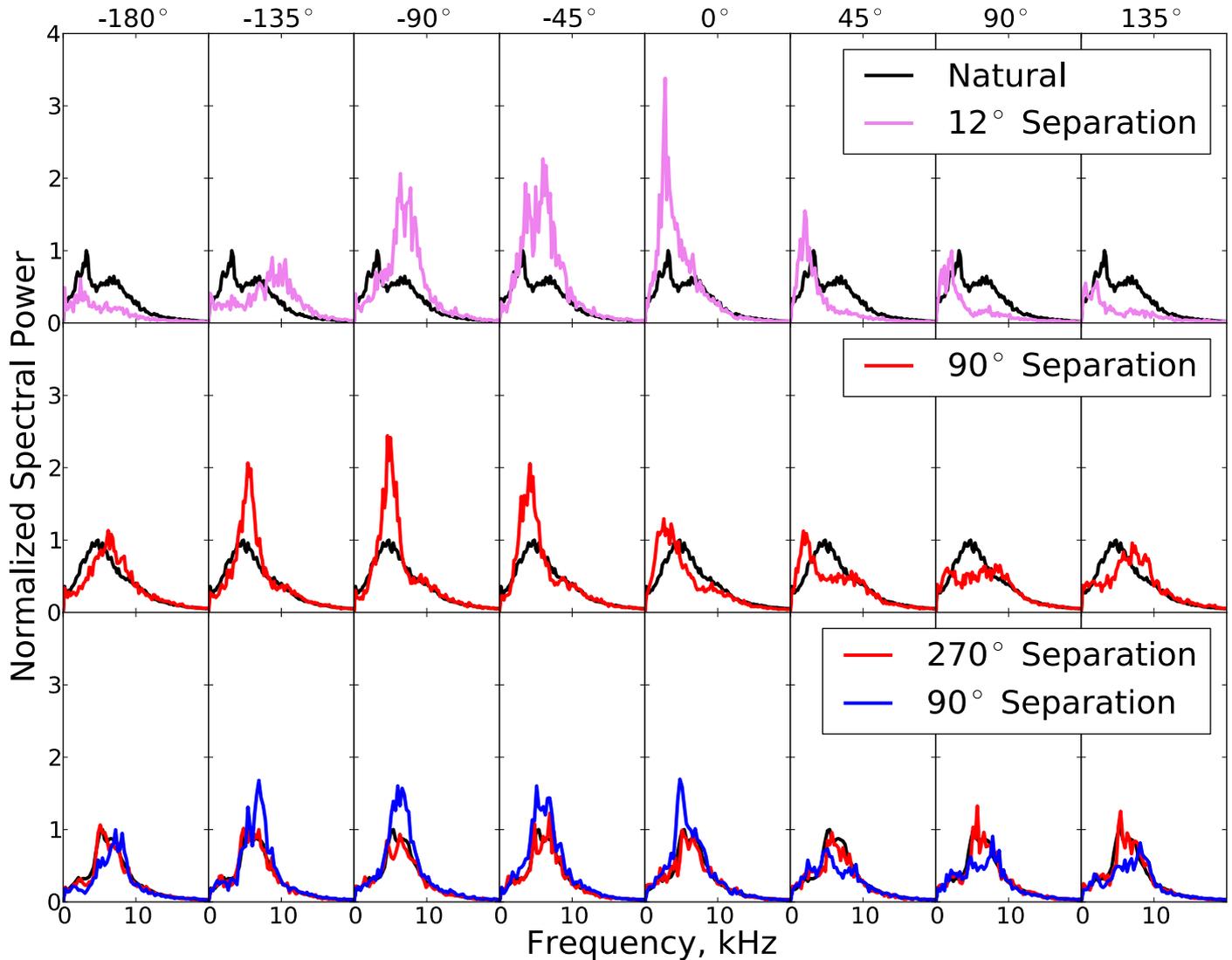
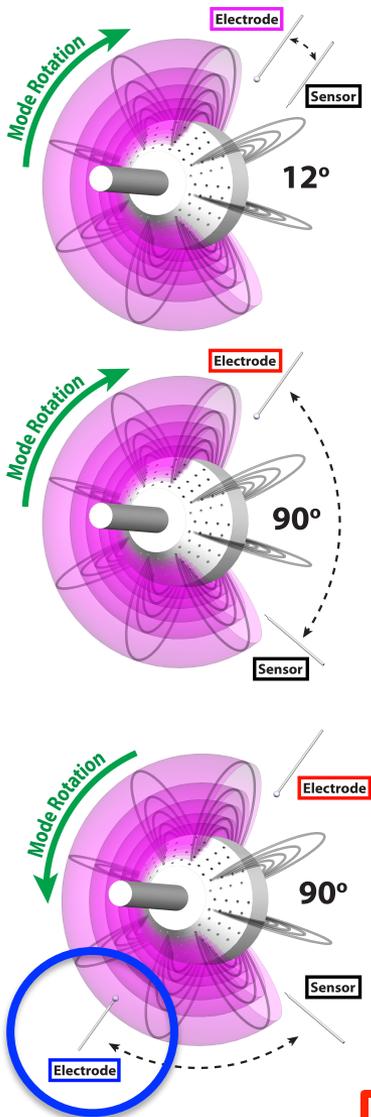
- Shift in phase of peak amplification and suppression
- Reduced response, particularly in suppression

Varying the Separation between the Sensor and Electrode



No response with effective 270° separation

Varying the Separation between the Sensor and Electrode



“Upstream” electrode produces similar response

Flux-Tube Averaged Gyro-Fluid Model



Electron diamagnetic and ion inertial currents

$$J_{\perp} = J_{dia} + J_{inertial}$$

Flux-Tube Average →

$$\int \frac{ds}{B} (\nabla_{\perp} \cdot J_{\perp}) = \begin{cases} -\frac{\hat{b} \cdot J_{\parallel}}{B} \\ 0 \\ I\delta(\vec{x} - \vec{x}_e) \end{cases}$$

Ionosphere

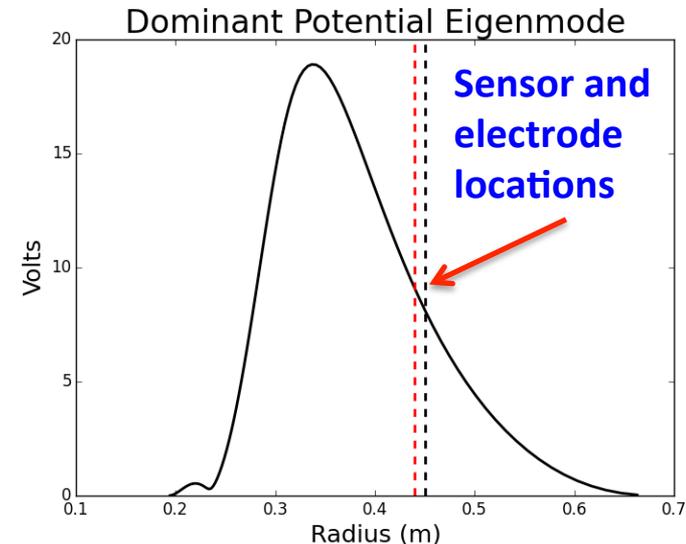
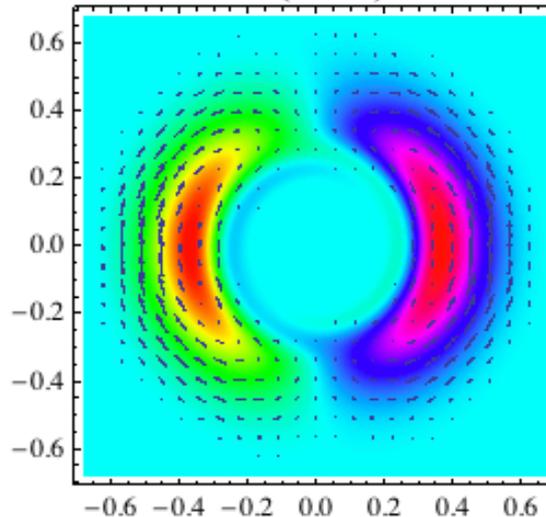
No FACs; CTX LDX

Feedback

- Linearized and flux-tube averaged gyro-fluid model (Drake and Antonsen, 1984) (Ricci, 2006)
- Linear eigenmode, radially broad, low order azimuthal structure
- Profiles consistent with measurements yield mode rotation of 4.5 kHz

$$\tilde{V}_p \quad (m = 1)$$

$$I = (|G|e^{i\varphi} - 1) \frac{\tilde{V}_P}{R_s}$$



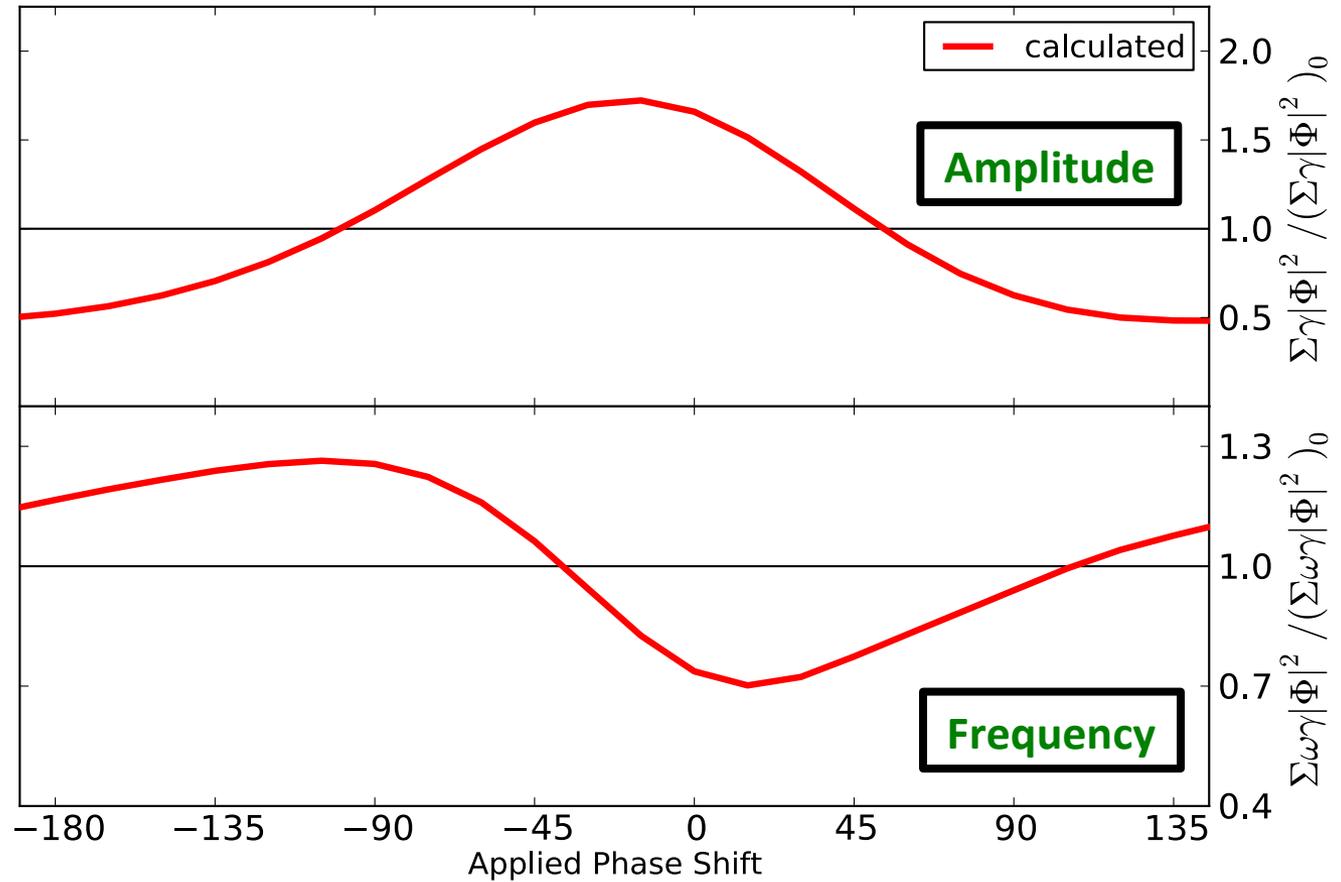
Flux-Tube Averaged Linear Model Shows Some Agreement



**Fixed gain of 4
360 Phase Scan**

**Band Integrated
(1-10 kHz)
Spectral Intensity**

**Intensity Weighted
Frequency (1-10 kHz)**



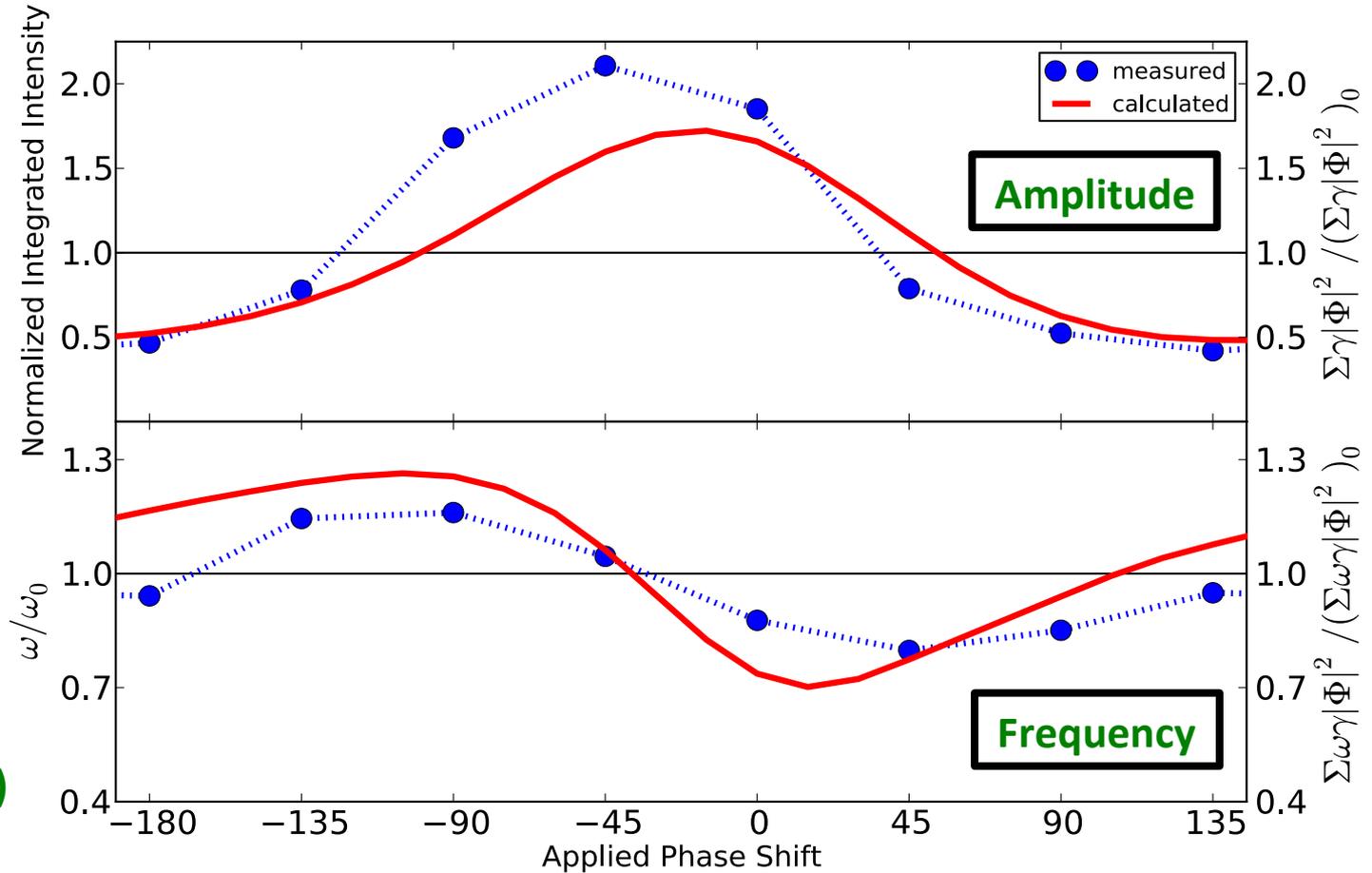
Flux-Tube Averaged Linear Model Shows Some Agreement



Fixed gain of 4
360 Phase Scan

Band Integrated
(1-10 kHz)
Spectral Intensity

Intensity Weighted
Frequency (1-10 kHz)



- Current-collection feedback in a nonlinear gyro-fluid simulation.
- Multiple independent feedback systems, and multipoint FPGA controlled feedback.
- Turbulence control on LDX with levitated superconducting dipole.

- Broadband current-collection feedback amplifies or suppresses the interchange-turbulence.
- Current-collection feedback is localized and in the direction of mode rotation.
- Depending on phase, feedback is a generator or a load, either injecting or extracting power from the fluctuations.
- A linear flux-tube averaged gyro-fluid model including a point current source shows some agreement with experiment.

Thanks to the help of many contributors:
Michael Mael, Jay Kesner, Darren Garnier,
Matthew Worstell, Matthew Stiles Davis,
Kristina Lynch, Abed Balbaky

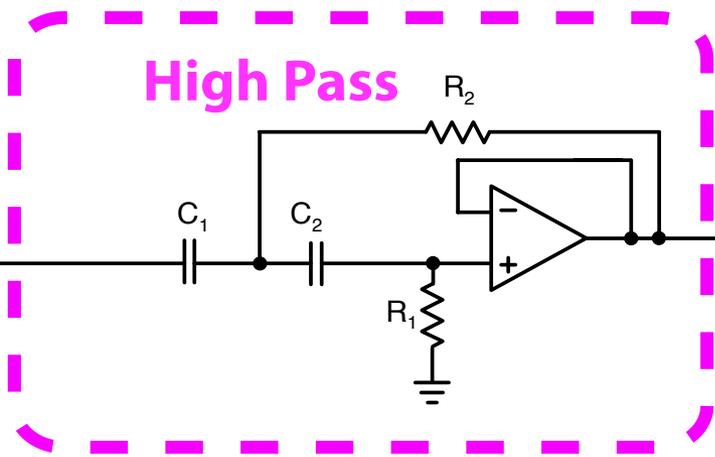
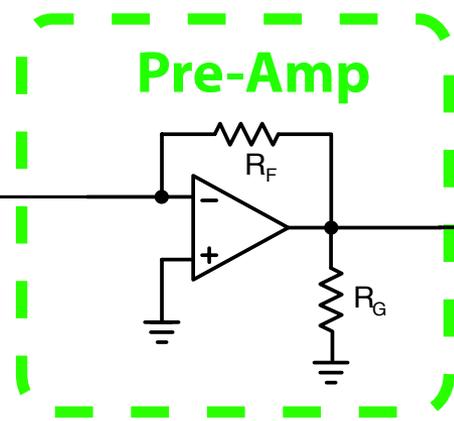
- Phase response and circuit
- Showing “current model”
- Showing full gyro-fluid model
- Experiments with parallel currents

Phase Shifting Circuit

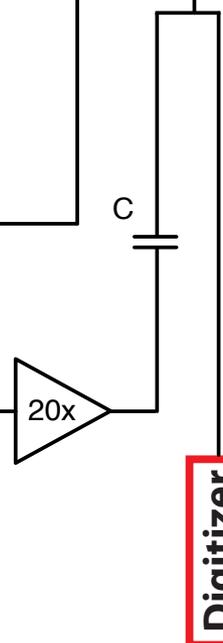
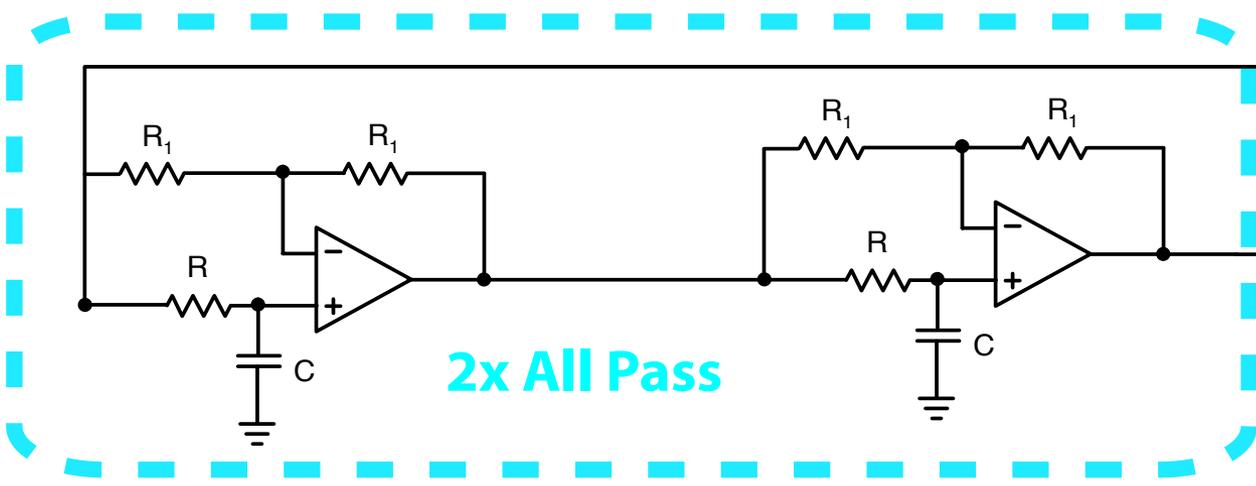


Sensor

Electrode



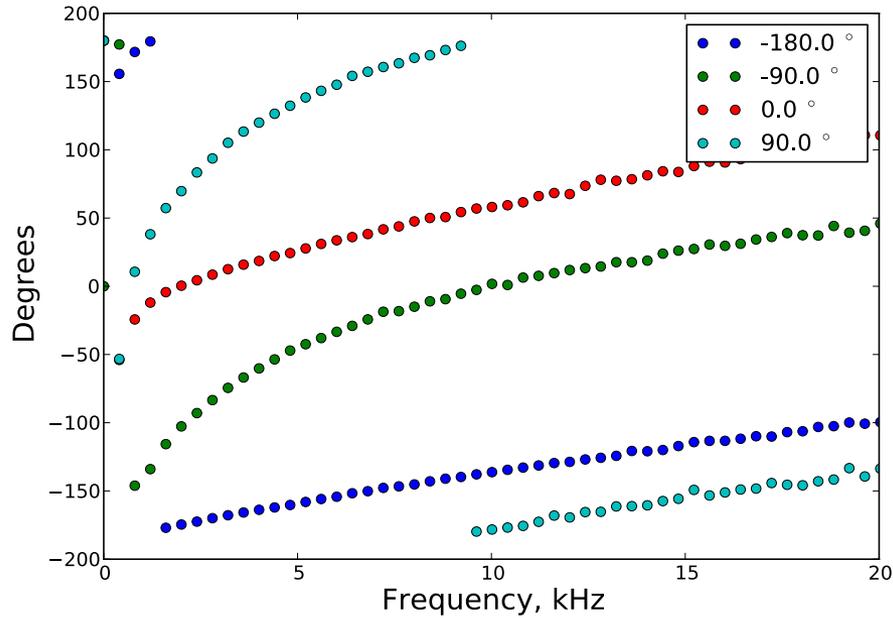
Digitizer



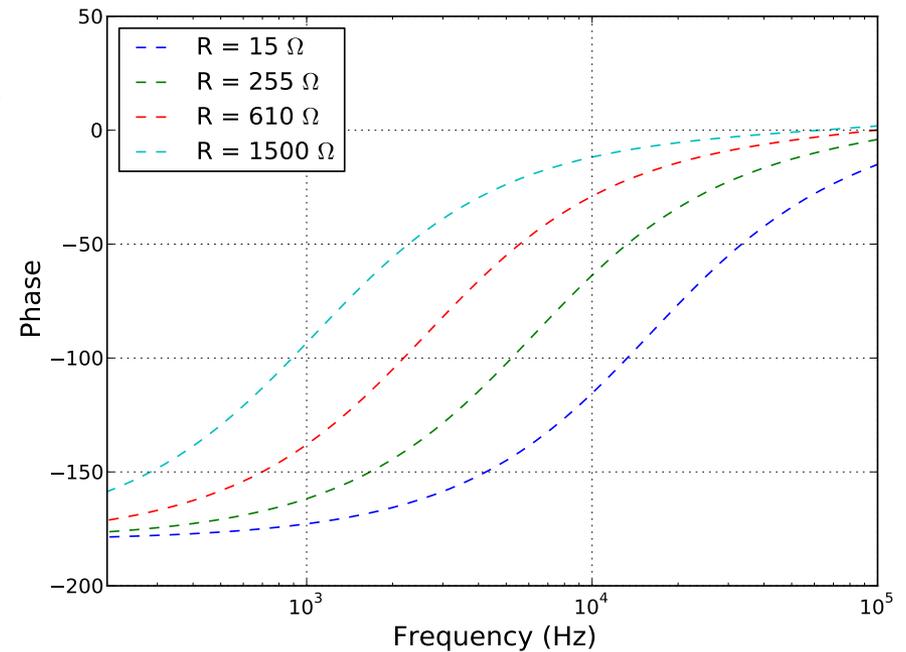
Phase Shifting Circuit



Measured Phase Shifts



All-Pass Phase Response

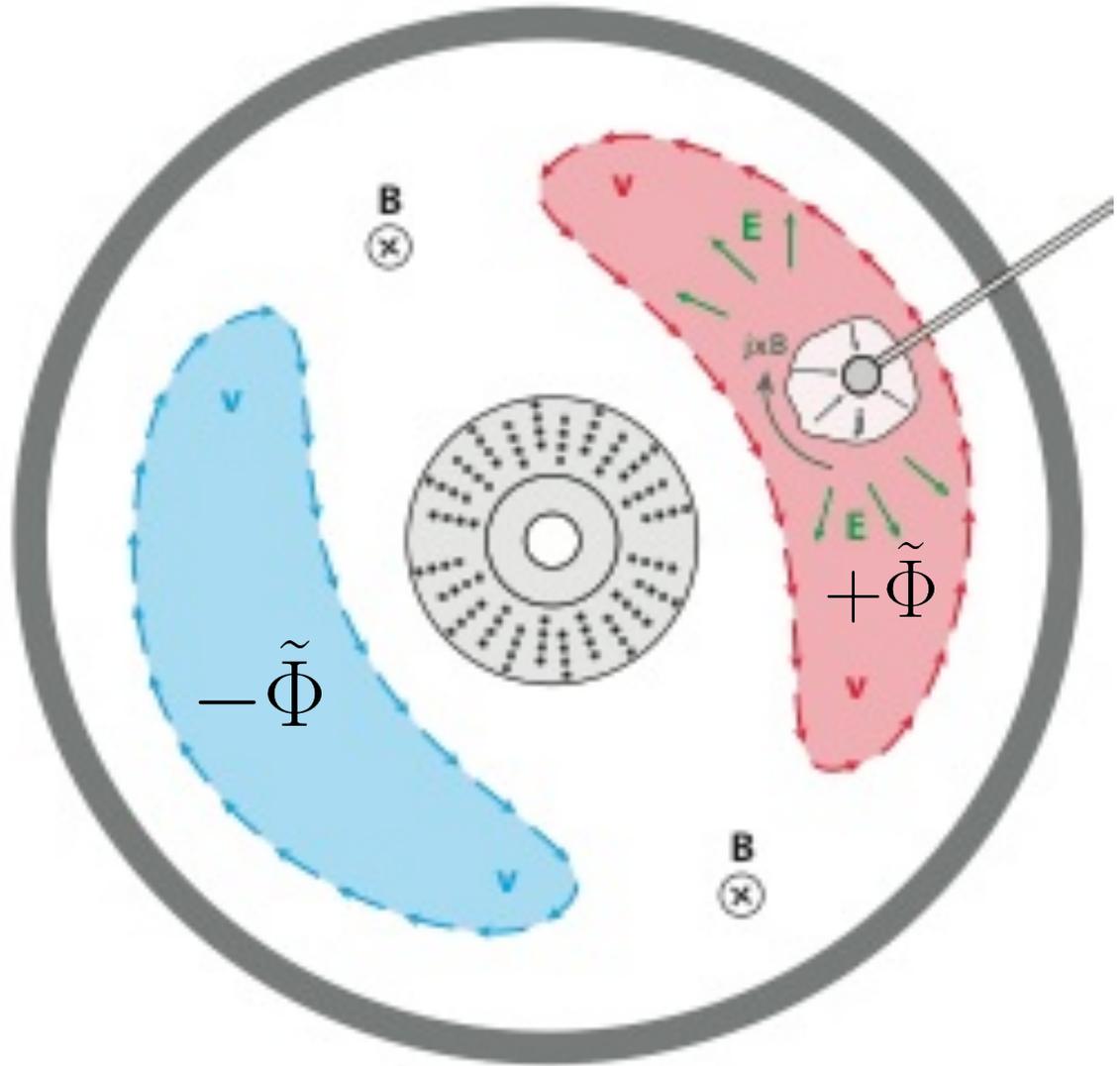


Defining Current-Collection Feedback

$$\rho \frac{\partial \vec{v}}{\partial t} = \vec{j} \times \vec{B} - \nabla.$$

$$\vec{v} \approx \frac{\vec{E} \times \vec{B}}{B^2}$$

$$\frac{\rho}{B^2} \frac{\partial E}{\partial t} = j$$



Defining Current and Power

$$\tilde{V}_S \approx \tilde{V}_P$$

$$\tilde{V}_A = G\tilde{V}_S \approx |G|e^{i\varphi}\tilde{V}_P$$

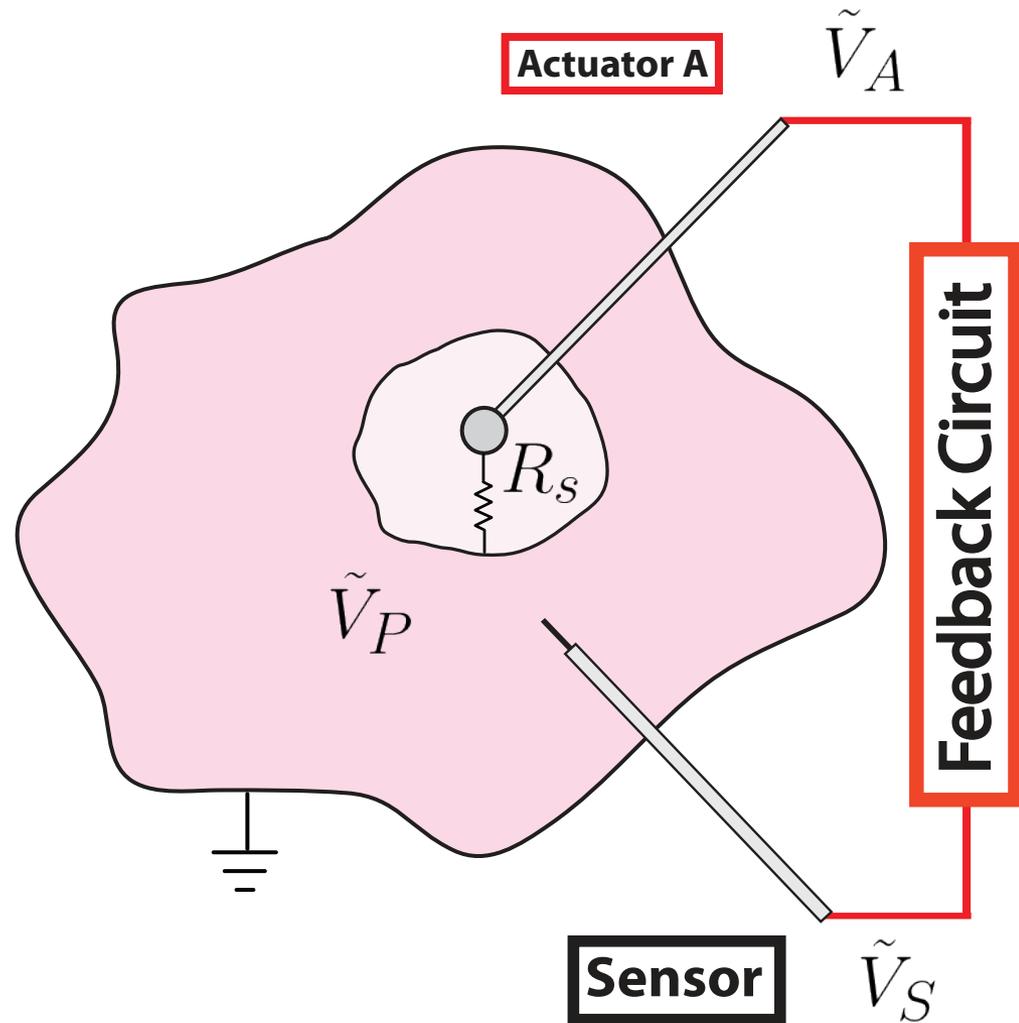
$$I = \frac{\tilde{V}_A - \tilde{V}_P}{R_s}$$

$$\approx (|G|e^{i\varphi} - 1) \frac{\tilde{V}_P}{R_s}$$

$$\tilde{P}_A = I\tilde{V}_A$$

$$\tilde{P}_s = I(\tilde{V}_A - \tilde{V}_P)$$

$$\tilde{P}_P = I\tilde{V}_P$$



Time Averaged Power in Frequency

$$P(t) = I(t)V(t) \quad \text{Instantaneous Power}$$

$$\langle P(t) \rangle = \langle I(t)V(t) \rangle = \frac{1}{T} \int_0^T I(t)V(t)dt \quad \text{Time Averaged Power (0 Hz)}$$

$$FFT(P(t)) = I(\omega) * V(\omega) = \int_{-\infty}^{+\infty} I(\omega')V(\omega - \omega')d\omega'$$

Time averaged power is the convolution with $\omega = 0$

$$FFT(P(t))[\omega = 0] = \int_{-\infty}^{+\infty} I(\omega')V(-\omega')d\omega' = \langle P(t) \rangle \quad (0 \text{ Hz})$$

$$I(\omega)V(-\omega) = (Y(\omega)V(\omega))V^*(\omega)$$



$$Y(\omega) = \frac{IV^*}{|V|^2} \longrightarrow \langle P(t) \rangle = \int_{-\infty}^{+\infty} Y(\omega)|V(\omega)|^2d\omega$$

Flux-Tube Averaged Gyro-Fluid Model



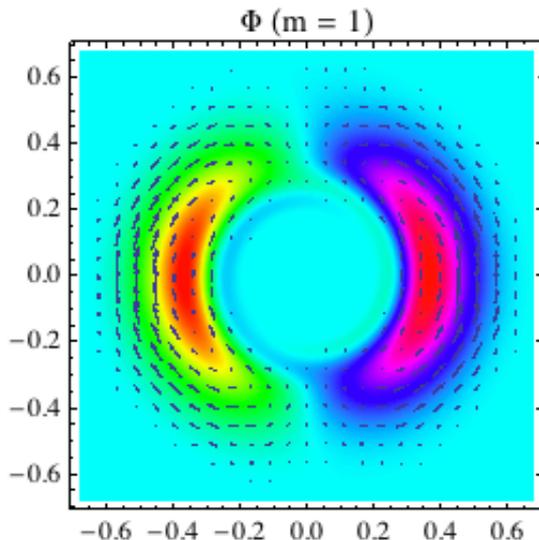
$$J_{\perp} = \frac{1}{B^2} B \times \nabla p_e + \frac{nM_i}{B^2} B \times \frac{dV_E}{dt}$$

diamagnetic inertial

$$v_e = \frac{E \times B}{B^2} - \frac{B \times \nabla p_e}{enB^2}$$

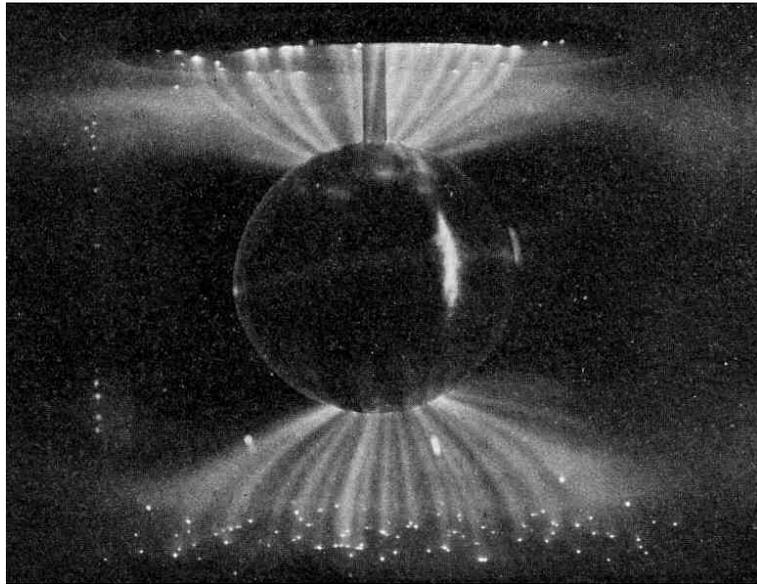
warm electrons

Flux-Tube Average $\left\{ \begin{array}{l} \nabla \cdot J_{\perp} = 0 \qquad \frac{\partial n}{\partial t} + \nabla \cdot n v_e = 0 \\ \frac{\partial p_e}{\partial t} + \nabla \cdot (p_e V_E) + (\gamma - 1) p_e \nabla \cdot V_E = \gamma \frac{2}{\omega_{ci}} \kappa \frac{\partial}{\partial \varphi} (p_e C_s^2) \end{array} \right\}$



- Linear eigenmode, radially broad, low order toroidal structure
- Eigenvalue is mode growth rate and rotation

$$\nabla \cdot J_{FB} = I \delta(\psi, \varphi) \qquad I = (|G| e^{i\varphi} - 1) \frac{\tilde{V}_P}{R_s}$$



Kristian Birkeland, 1913

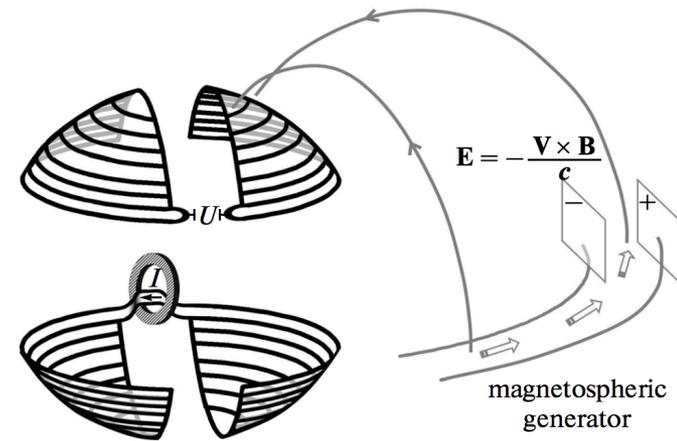


Fig. 3. Schematic location of plates on the dipole frame for measuring the potential and current between the dawn and dusk sides. The scheme of the magnetospheric generator is also shown on the dusk side.

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